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### KAOS Construct Analysis using the UEML Approach Template

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# **Namur University**

## **Computer Science Department**



## **KAOS Construct Analysis using the UEML Approach Template**

**(Technical report)**

**Raimundas Matulevičius  
and Patrick Heymans**



Namur, Belgium  
2005



## Outline

KAOS : Achieve goal .....	5
KAOS : Agent.....	9
KAOS : Assignment .....	13
KAOS : Avoid goal.....	17
KAOS : Boundary condition.....	21
KAOS : Cease goal .....	25
KAOS : Conflict .....	29
KAOS : Control .....	33
KAOS : Domain property .....	35
KAOS : Environment agent.....	39
KAOS : Event .....	41
KAOS : Expectation .....	43
KAOS : Goal.....	47
KAOS : Goal refinement .....	51
KAOS : Input .....	55
KAOS : Maintain goal .....	59
KAOS : Monitor .....	63
KAOS : Object.....	65
KAOS : Operation.....	69
KAOS : Operationalisation .....	73
KAOS : Output .....	79
KAOS : Performance .....	83
KAOS : Requirement.....	87
KAOS : Softgoal .....	91
KAOS : Software agent .....	93



## KAOS : Achieve goal

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<b>Authors:</b>	Raimundas Matulevičius
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*Achieve goals* are goals requiring that some property eventually holds.

*Achieve goals* state that some target condition should hold in some (bounded) future state.

### 1. Preamble

#### Builds on

Goal

#### Built on by

#### Construct name

Achieve goal

#### Alternative construct names

goal, requiring that a property eventually holds

#### Related, but distinct construct names

goal with a pattern achieve

#### Related terms

*Goal* : a prescriptive assertion capturing some objective to be met by cooperation of agents from the agent model.

*Maintain goal*: a goal requiring that some property always holds.

*Avoid goal*: a goal requiring that some property never holds.

*Cease goal*: a goal requiring that some property eventually stops to hold.

*Softgoal*: goal that do not have a clear-cut criterion for their satisfaction.

*Terminal goals*: a goal which has no G-refinement.

*Requirement*: a goal assigned to an agent in the software to be.

*Expectation (assumption)*: a goal assigned to an agent in the environment.

**Comment:** Can a goal with a pattern be softgoal, terminal goal (requirement and expectation)?

#### Language

KAOS, <http://www2.info.ucl.ac.be/research/projects/AVL/ReqEng.html>

#### Diagram type

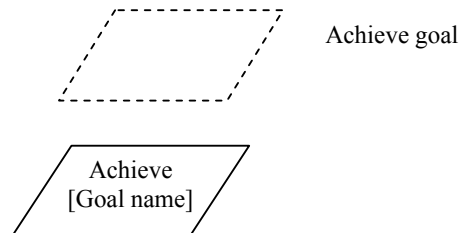
Goal model

## 2. Presentation

**Builds on**

**Built on by**

**Icon, line style, text**



**User-definable attributes**

**Relations to other constructs**

**Diagram layout conventions**

**Other usage conventions**

## 3. Representation

**Builds on**

**Built on by**

**Instantiation level**

Both type and instance level

### Classes of things

1:1, “*goalOwner*” **played by** *StakeholderThing*.

Describing *goal owner* which holds the goal. Class *StakeholderThing* has a characteristic *holds goal*.  
*StakeholderThing* is subclass of the *BWW-HumanThing*.

1:1, “*concernedObject*” **played by** *AllThing*.

Describing *object* concerned by a *goal*.

**Comment:** *Achieve goal* has the same classes as a *goal*. It belongs to a *goal owner* and has the sub-properties. These classes are described here as they are used in property definition.

### Properties (and relationships)

1:1, “*theAchieveGoal*” **played by** *ComplexTransformationLaw*.

**Belongs to:** 0:1 [1:1], *goalOwner*.

**Transformation law:** a change is required between a state where the *concerned object* properties are false and one where they are true.

Representing the achieve goal which is held by a goal owner and requires that some concerned object properties eventually hold.

**Comment:** For more *achieve goal* properties (such as *concExplicitObjAttribute*, *concImplicitObjAttribute*, *attributeName*, *attributeDef*, *attributeFormalSpec*, *attributePriority*, and *attributeCategory*), see *goal*.

## **Behaviour**

Existence

## **Modality (permission, recommendation etc)**

Intention of a goal owner;

## **4. Open Issues**

## **Change List**





## KAOS : Agent

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An *agent* is an active object (or “processor”) which plays a specific role towards goal achievement by controlling specific object behaviours. The focus is thus on a specific role rather than a specific individual.

*Agents* are active objects, that is, they are capable of performing operations.

### 1. Preamble

#### Builds on

Object

#### Built on by

Environment agent  
Software agent

#### Construct name

Agent

#### Alternative construct names

An active object  
A processor

#### Related, but distinct construct names

- *Environment agent* : e.g., pre-existing software component, sensor, actuator, human, organizational unit, etc.
- *Software agent* : an agent in the system-to-be.

#### Related terms

#### Language

KAOS,  
<http://www2.info.ucl.ac.be/research/projects/AVL/ReqEng.html>

#### Diagram type

Agent model

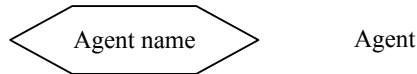
### 2. Presentation

#### Builds on

## Built on by

Assignment,  
Performance,  
Controls,  
Monitors

## Icon, line style, text



## User-definable attributes

[1:1] *Name*: String = "". A string allowing for unambiguous reference to corresponding instances at the application level.

[1:1] *Def*: FreeText = "". Free text used for precise, unambiguous definition of the corresponding instances at the application level.

## Relations to other constructs

- Belongs 1:1 to agent model.
- 1:n [1:1] *responsibleAgent* : assignment. Agent has assignment to satisfy the goal.

**Comment:** Agents are objects. This means that agent could also not be a responsible agent as they could be defined in the object hierarchy.

- 0:n [1:n] *performs* : operation. Agent performs operation in order to satisfy operationalised by this operation goal, which is assigned to this agent.
- 0:n [0:n] *monitors* : object. Agent monitors ("reads") the attribute of the object.
- 0:n [0:n] *controls* : object. Agent controls ("writes") the attribute of the object.

## Diagram layout conventions

## Other usage conventions

# 3. Representation

## Builds on

## Built on by

## Instantiation level

Both type and instance level

## Classes of things

1:1 "*theAgent*" **played by** *ActiveComponentThing*.  
Represents the agent.

1:1 "*monitoredControlledObject*" **played by** *ComponentThing*.  
Represents *object*, controlled or monitored by an agent.

## Properties (and relationships)

1:1 [1:1], "*attributeName*" **played by** *AnyRegularProperty*.  
**Belongs to:** *theAgent*.  
Represents *agent* attribute *name*.

1:1 [1:1], “*attributeDef*” **played by** *AnyRegularProperty*.

**Belongs to:** *theAgent*.

Represents *agent attribute def*.

1:n [1:n], “*monitoredImplicitObjAttribute*” **played by** *EmergentBindingMutualProperty*

**Belongs to:** 0:n [0:n], *monitoredControlledObject*

**Belongs to:** 0:n [0:n], *theAgent*

An *agent* monitors an *object*, without defining the concrete *attribute* of the control.

**Also represented:** *Monitors*.

1:n [1:n], “*monitoredExplicitObjAttribute*” **played by** *EmergentBindingMutualProperty*

**Belongs to:** 0:n [0:n], *monitoredControlledObject*

**Belongs to:** 0:n [0:n], *theAgent*

An *agent* monitors an *object attribute*.

**Also represented:** *Monitors*.

1:n [1:n], “*controlledImplicitObjAttribute*” **played by** *EmergentBindingMutualProperty*

**Belongs to:** 0:n [0:n], *monitoredControlledObject*

**Belongs to:** 0:1 [0:n], *theAgent*

An *agent* controls an *object*, without defining the concrete *attribute* of the control.

**Also represented:** *Controls*.

1:n [1:n], “*controlledExplicitObjAttribute*” **played by** *EmergentBindingMutualProperty*

**Belongs to:** 0:n [0:n], *monitoredControlledObject*

**Belongs to:** 0:1 [0:n], *theAgent*

An *agent* controls an *object attribute*.

**Also represented:** *Controls*.

## Behaviour

Existence

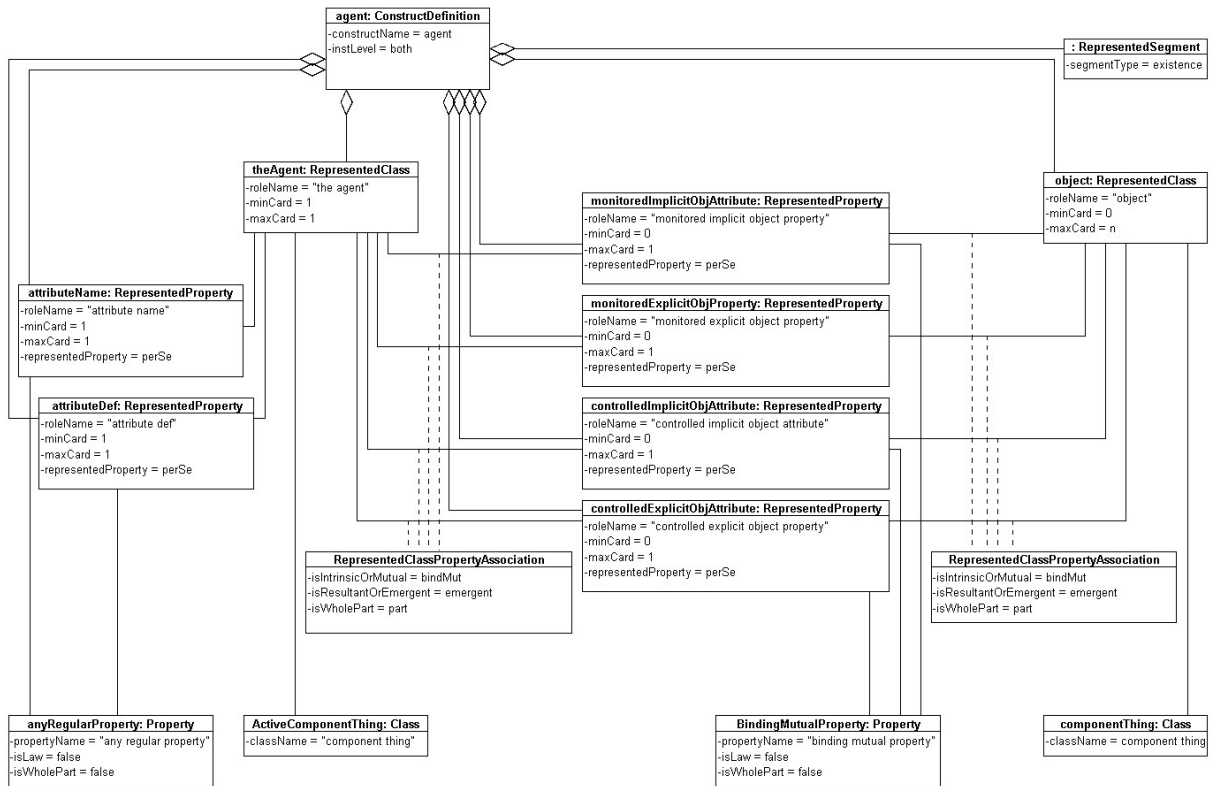
## Modality (permission, recommendation etc)

Regular assertion

## 4. Open Issues

TBF – *Dependency* constraint between agents as through goal or through operation.

TBF – A *goal* defines a set of admissible histories in the composed system. Intuitively, a history is a temporal sequence of states of the system. Specify *Scenario*, *Snapshot*, *Interaction*, *Source*, *Target*, and *State transition* constraints. This is related to *Agent*, *Event*, and *Operation* constraints.



## KAOS : Assignment

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<b>Authors:</b>	Raimundas Matulevičius
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The *Assignment* is introduced as target of an OR-Assignment meta-relationship from *Goal* to capture alternative assignments of the same terminal goal to different *agents*; alternative assignments result in different system proposals in which more or less is automated.

### 1. Preamble

**Builds on**

**Built on by**

**Construct name**

Assignment

**Alternative construct names**

Responsibility assignment

**Related, but distinct construct names**

**Related terms**

**Language**

KAOS,  
<http://www2.info.ucl.ac.be/research/projects/AVL/ReqEng.html>

**Diagram type**

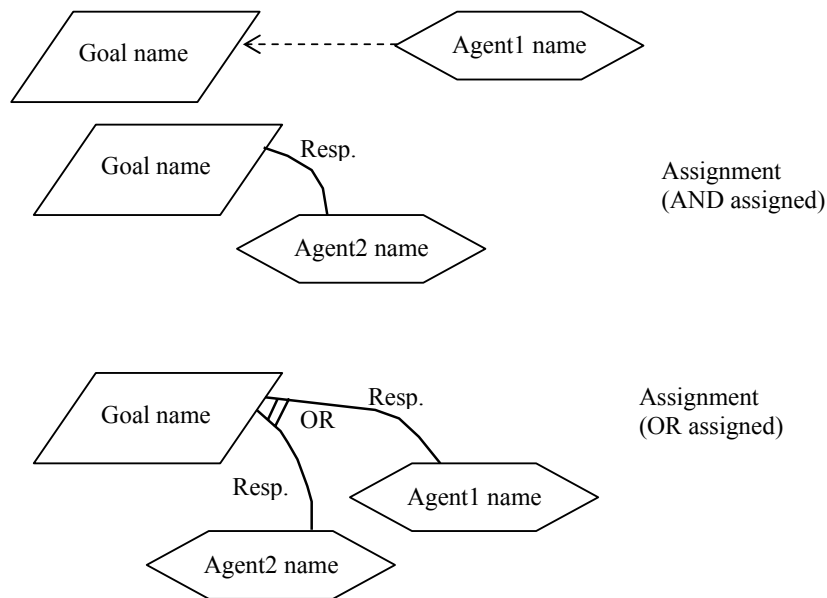
Agent model

### 2. Presentation

**Builds on**

**Built on by**

## Icon, line style, text



## User-definable attributes

[0:1] *AltName* : String = "". Name of alternative OR-assignments.

## Relations to other constructs

- Belongs to 1..1 agent model.
- 1:1 [0:n], *assignedGoal*: goal. A *goal*, if it is a terminal goal, could be assigned.
- 1:1 [1:n], *responsibleAgent*: agent. Responsible agent (software agent or environment agent) is responsible for goal satisfaction.

## Diagram layout conventions

## Other usage conventions

## 3. Representation

### Builds on

Goal  
Agent

### Built on by

### Instantiation level

Instance and type level

### Classes of things

1:1 "*responsibleAgent*" **played by** *ActiveComponentThing*.  
Represents the responsible agent.

1:1, "*goalOwner*" **played by** *StakeholderThing*.  
Describing *goal owner* which holds the goal. Class *StakeholderThing* has a characteristic *holds goal*.  
*StakeholderThing* is subclass of the *BWW-HumanThing*.

## Properties (and relationships)

1:1, “theGoal” played by *ComplexLawProperty*.

**Belongs to:** 0:1 [1:1], *goalOwner*.

**Law:** restricts the the possible values of the *object* attributes.  
Representing the goal which is held by a goal owner.

1:1, “terminalGoal” played by *StateLaw*.

**Belongs to:** 0:1 [1:1], *goalOwner*.

**Sub-property:** 1:1 [1:1], *theGoal*.

**State law:**  $\forall g \in \text{Goal}, \forall a \in \text{Assignment}, a.\text{assignedGoal} = g$   
 $\Rightarrow \neg \exists gr \in G\text{-refinement: } gr.\text{superGoal} = g$

Only terminal goals can by assigned.

1:1, “theAssignment” played by *ComplexBindingMutualProperty*.

**Type:** OR relationship.

**Belongs to:** 1:1 [1:n] *responsibleAgent*.

**Sub-property:** 1:1 [0:n] *terminalGoal*.

Describing the *assignment*.

0:1, “attributeAltName” played by *AnyRegularProperty*.

**Sub-property:** *theAssignment*.

Represents *assignment* attribute *altName*.

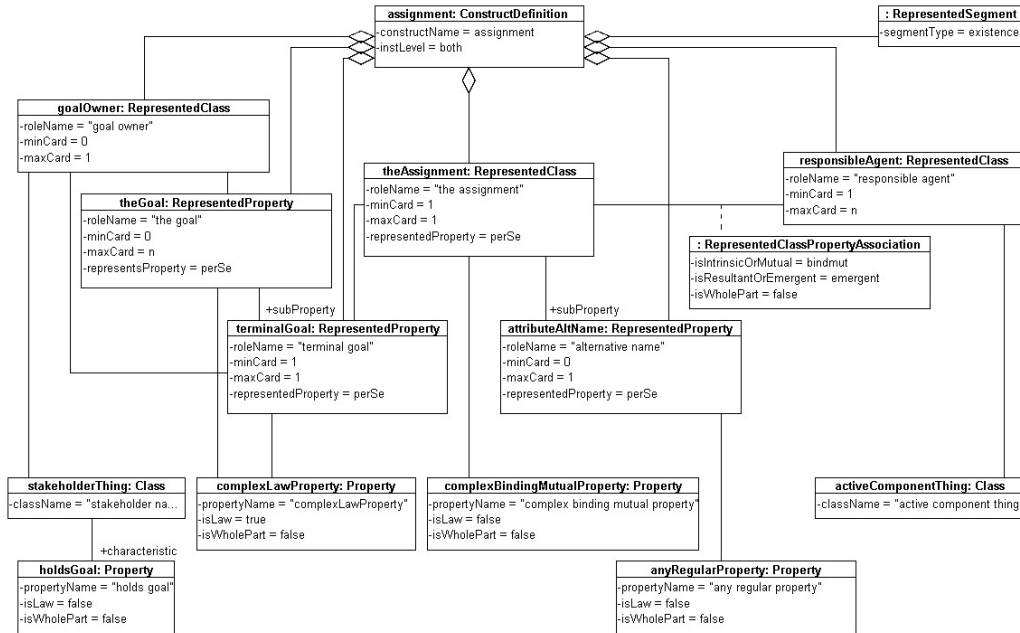
## Behaviour

Existence

## Modality (permission, recommendation etc)

Regular assertion

## 4. Open Issues







## KAOS : Avoid goal

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*Avoid goals* are goals requiring that some property never holds.

*Avoid goals* state that some target condition on system states should never hold under some current condition.

### 1. Preamble

#### Builds on

Goal

#### Built on by

#### Construct name

Avoid goal

#### Alternative construct names

goal, requiring that some property never holds

#### Related, but distinct construct names

goal with a pattern avoid

#### Related terms

*Goal* : a prescriptive assertion capturing some objective to be met by cooperation of agents from the agent model.

*Maintain goal*: a goal requiring that some property always holds.

*Cease goal*: a goal requiring that some property eventually stops to hold.

*Achieve goal*: a goal requiring that some property eventually hold.

*Softgoal*: goal that do not have a clear-cut criterion for their satisfaction.

*Terminal goals*: a goal which has no G-refinement.

*Requirement*: a goal assigned to an agent in the software to be.

*Expectation (assumption)*: a goal assigned to an agent in the environment.

**Comment:** Can a goal with a pattern be softgoal, terminal goal (requirement and expectation)?

#### Language

KAOS, <http://www2.info.ucl.ac.be/research/projects/AVL/ReqEng.html>

#### Diagram type

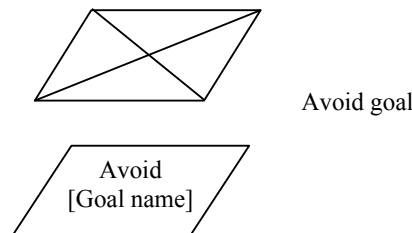
Goal model

## 2. Presentation

**Builds on**

**Built on by**

**Icon, line style, text**



**User-definable attributes**

**Relations to other constructs**

**Diagram layout conventions**

**Other usage conventions**

## 3. Representation

**Builds on**

**Built on by**

**Instantiation level**

Both type and instance level

### Classes of things

1:1, “*goalOwner*” **played by** *StakeholderThing*.

Describing *goal owner* which holds the goal. Class *StakeholderThing* has a characteristic *holds goal*.  
*StakeholderThing* is subclass of the *BWW-HumanThing*.

1:1, “*concernedObject*” **played by** *AllThing*.

Describing *object* concerned by a goal.

**Comment:** *Avoid goal* has the same classes as a *goal*. It belongs to a *goal owner* and has the sub-properties. These classes are described here as they are used in property definition.

### Properties (and relationships)

1:1, “*theAvoidGoal*” **played by** *ComplexStateLaw*.

**Belongs to:** 0:1 [1:1], *goalOwner*.

**State law:** indicates states that cannot be in concerned object.

Representing the avoid goal which is held by a goal owner and requires some properties of the concerned object never holds.

**Comment:** For more *avoid goal* properties (such as *concExplicitObjAttribute*, *concImplicitObjAttribute*, *attributeName*, *attributeDef*, *attributeFormalSpec*, *attributePriority*, and *attributeCategory*), see *goal*.

## **Behaviour**

Existence

## **Modality (permission, recommendation etc)**

Intention of a goal owner;

## **4. Open Issues**

## **Change List**



## KAOS : Boundary condition

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<b>Distribution list:</b>	DEM
<b>Document history:</b>	

*Boundary condition* describes inconsistencies in the considered domain – this means that two or more different goals could not be achieved together.

### 1. Preamble

**Builds on**

**Built on by**

**Construct name**

Boundary condition

**Alternative construct names**

Inconsistencies in the considered domain

**Related, but distinct construct names**

**Related terms**

Conflict

**Language**

KAOS,  
<http://www2.info.ucl.ac.be/research/projects/AVL/ReqEng.html>

**Diagram type**

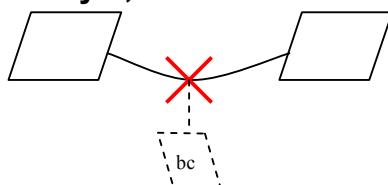
Goal model

### 2. Presentation

**Builds on**

**Built on by**

**Icon, line style, text**



Boundary condition

## User-definable attributes

[1:1] *Name*: String = “”. A string allowing for unambiguous reference to corresponding instances at the application level.

[1:1] *Def*: FreeText = “”. Free text used for precise, unambiguous definition of the corresponding instances at the application level.

[0:1] *FormalSpec*: KAOS real time temporal logic expression. Its values at the application level specify the corresponding *Def* attribute in the KAOS real-time temporal logic.

[0:1] *Likelihood* : propability  $\in [0..1]$ . Its values at the application level specify how likely the boundary condition is.

[0:1] *Criticality* : set\_of{critical, ..., not critical}. Its values at the application level specify how severe the consequences of the resulting conflict are.

## Relations to other constructs

Belongs 1:1 to goal model.

1:1 [1:1], *existUnder* : conflict. Conflict exist only under some boundary condition.

## Diagram layout conventions

## Other usage conventions

# 3. Representation

## Builds on

Conflict

## Built on by

## Instantiation level

Instance level

**Comment:** can we define classes of *boundary conditions*?

## Classes of things

## Properties (and relationships)

1:1, “*theBoundaryCondition*” **played by** *StateLaw*.

**Type:** *Boolean*, **default value:** *true*.

**Sub-property:** 1:1 [1:1] *theConflict*.

**State law:** two (or more) goals in the same *G-refinement* cannot be satisfied together.  
Describing *boundary condition*.

1:1 [1:1], “*attributeName*” **played by** *AnyRegularProperty*.

**Sub-property:** *theBoundaryCondition*.

Represents *boundary condition* attribute *name*.

1:1 [1:1], “*attributeDef*” **played by** *AnyRegularProperty*.

**Sub-property:** *theBoundaryCondition*.

Represents *boundary condition* attribute *def*.

1:1 [1:1], “*attributeFormalSpec*” **played by** *AnyRegularProperty*.

**Sub-property:** *theBoundaryCondition*.

Represents *boundary condition* attribute *formalSpec*.

0:1 [1:1], “*attributeLikelihood*” **played by** *AnyRegularProperty*.

**Sub-property:** *theBoundaryCondition*.

Represents *boundary condition* attribute *likelihood*.

0:1 [1:1], “*attributeCritically*” **played by** *AnyRegularProperty*.

**Sub-property:** *theBoundaryCondition*.

Represents *boundary condition* attribute *critically*.

## Behaviour

State

“*logicalInconsistency*” **played by** *unstableState*.

**Defining property:** *theBoundaryCondition*,

**State constraint:** Two or more different goals could not be achieved together.

## Modality (permission, recommendation etc)

Regular assertion

## 4. Open Issues

TBD – describe state law in a more formal way.





## KAOS : Cease goal

<b>Document type:</b>	Working document
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<b>Authors:</b>	Raimundas Matulevičius
<b>Distribution list:</b>	DEM
<b>Document history:</b>	

*Cease goals* are goals requiring that some property eventually stops to holds.  
*Cease goals* state that some target condition should not hold in some (bounded) future state.

### 1. Preamble

#### Builds on

Goal

#### Built on by

#### Construct name

Cease goal

#### Alternative construct names

goal, requiring that some property eventually stops to hold.

#### Related, but distinct construct names

goal with a pattern cease

#### Related terms

*Goal* : a prescriptive assertion capturing some objective to be met by cooperation of agents from the agent model.

*Maintain goal*: a goal requiring that some property always holds.

*Avoid goal*: a goal requiring that some property never holds.

*Achieve goal*: a goal requiring that some property eventually hold.

*Softgoal*: goal that do not have a clear-cut criterion for their satisfaction.

*Terminal goals*: a goal which has no G-refinement.

*Requirement*: a goal assigned to an agent in the software to be.

*Expectation (assumption)*: a goal assigned to an agent in the environment.

**Comment:** Can a goal with a pattern be softgoal, terminal goal (requirement and expectation)?

#### Language

KAOS, <http://www2.info.ucl.ac.be/research/projects/AVL/ReqEng.html>

#### Diagram type

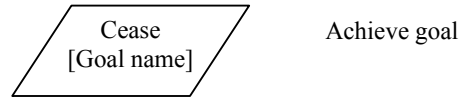
Goal model

## 2. Presentation

**Builds on**

**Built on by**

**Icon, line style, text**



**User-definable attributes**

**Relations to other constructs**

**Diagram layout conventions**

**Other usage conventions**

## 3. Representation

**Builds on**

**Built on by**

**Instantiation level**

Both type and instance level

### Classes of things

1:1, “*goalOwner*” **played by** *StakeholderThing*.

Describing *goal owner* which holds the goal. Class *StakeholderThing* has a characteristic *holds goal*. *StakeholderThing* is subclass of the *BWW-HumanThing*.

1:1, “*concernedObject*” **played by** *AllThing*.

Describing *object* concerned by a *goal*.

**Comment:** *Cease goal* has the same classes as a *goal*. It belongs to a *goal owner* and has the sub-properties. These classes are described here as they are used in property definition.

### Properties (and relationships)

1:1, “*theCeaseGoal*” **played by** *ComplexTransformationLaw*.

**Belongs to:** 0:1 [1:1], *goalOwner*.

**Transformation law:** a change is required between a state where the *concerned object* properties are *true* and one where they are *false*.

Representing the *cease goal* which is held by a *goal owner* and requires that some *concerned object* properties eventually stops to hold.

**Comment:** For more *cease goal* properties (such as *concExplicitObjAttribute*, *concImplicitObjAttribute*, *attributeName*, *attributeDef*, *attributeFormalSpec*, *attributePriority*, and *attributeCategory*), see *goal*.

### Behaviour

Existence

**Modality (permission, recommendation etc)**

Intention of a goal owner;

## **4. Open Issues**

### **Change List**



## KAOS : Conflict

<b>Document type:</b>	Working document
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Two or more goals are considered to be *conflicting* when under some boundary condition the goals become logically inconsistent in the considered domain – these goals could not be achieved together.

Goals  $G_1$ ,  $G_2$ , ...,  $G_n$  are said to be *conflicting* (or “divergent”) if under some boundary condition the goals become logically inconsistent in the domain considered, that is, they cannot be achieved altogether.

### 1. Preamble

**Builds on**

**Built on by**

**Construct name**

Conflict

**Alternative construct names**

Conflicting goals

Divergent goals

**Related, but distinct construct names**

**Related terms**

**Language**

KAOS,

<http://www2.info.ucl.ac.be/research/projects/AVL/ReqEng.html>

**Diagram type**

Goal model

### 2. Presentation

**Builds on**

**Built on by**

**Icon, line style, text**



Conflict

## User-definable attributes

### Relations to other constructs

2:n [0:n], *conflictBetweenGoals* : goals.  
0:n [0:n], *isInDomain* : domain properties.  
1:1 [1:1], *existUnder*: boundary condition.

### Diagram layout conventions

Cross between conflicting goals is represented in red.

### Other usage conventions

## 3. Representation

### Builds on

Two or more *goals*

### Built on by

Boundary condition  
Domain property

### Instantiation level

Instance level

**Comment:** can we define classes of conflicts?

### Classes of things

1:1, “*goalOwner*” **played by** *StakeholderThing*.  
Describing *goal owner* which holds the goal. Class *StakeholderThing* has a characteristic *holds goal*.  
*StakeholderThing* is subclass of the *BWW-HumanThing* (specified in *goal* template).  
If goals are conflicting, this means conflict between the goal owners.

1:1, “*concernedObject*” **played by** *ComponentThing*.  
Describing *object* concerned by a *goal*. This object is characterised by a *domain property*.

### Properties (and relationships)

1:1, *theConflict* **played by** *MutualProperty*. Describing the *conflict*.  
**Sub-property of** 2:n [0:n] *theGoal*.  
**Sub-property of** 0:n [0:n] *domainHypothesis*.  
**Sub-property of** 0:n [0:n] *domainInvariant*.  
Conflict specifies mutual property between two or more goal owners (we consider what two conflicting goals have different goal owners).

**Comment:** *theGoal* property is specified in the template for the *goal* construct.

1:1 [1:1], *boundaryCondition* **played by** *StateLaw*  
**Sub-property of** 1:1 [1:1] *theConflict*.  
**State law:** *Conflict* exist under some boundary condition.  
The conflict exists only if some boundary condition, which defines why two or more goals can not be satisfied together exists.  
**Also represented by:** *boundary condition*.  
0:n [0:n], *domainHypothesis* **played by** *AnyProperty*.  
Conflicts are described in the domain which is specified by the *domain properties*.  
**Also represented by:** *domain property*.

0:n [0:n], *domainInvariant* played by *AnyProperty*.

Conflicts are described in the domain which is specified by the *domain properties*.

Also represented by: *domain property*.

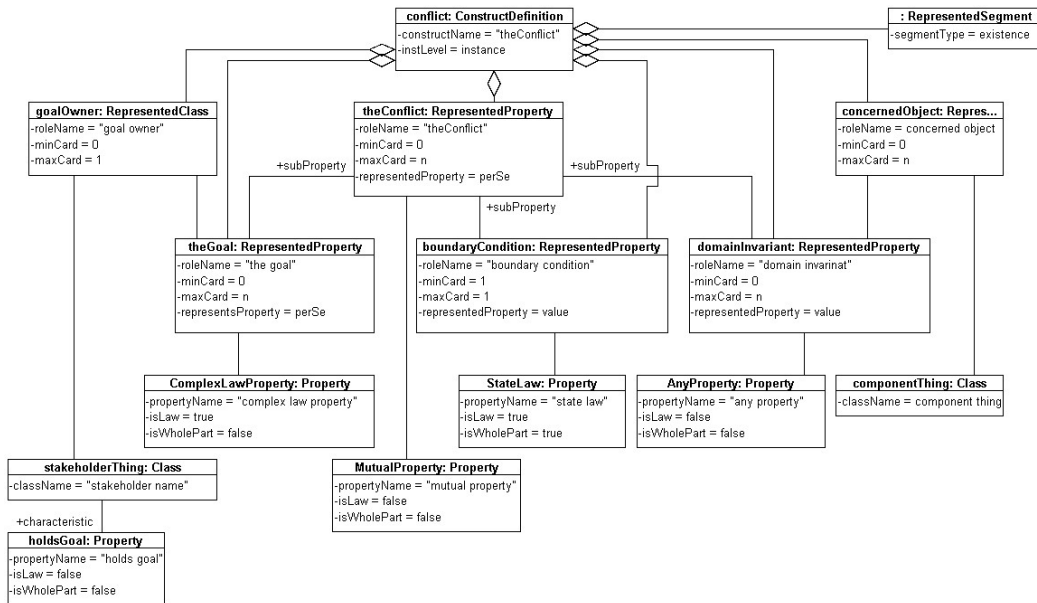
## Behaviour

Regular assertion

## Modality (permission, recommendation etc)

Obligation of *Boundary Condition*.

## 4. Open Issues







## KAOS : Control

<b>Document type:</b>	Working document
<b>Domain/Task/Topic:</b>	DEM / UEMML / Approaches
<b>Version:</b>	
<b>Date:</b>	2005.11.30
<b>Status:</b>	2 <sup>nd</sup> iteration
<b>Authors:</b>	Raimundas Matulevičius
<b>Distribution list:</b>	DEM
<b>Document history:</b>	

*Agent* controls (“writes”) the value of the *object* attribute.

### 1. Preamble

**Builds on**

**Built on by**

**Construct name**

Controls

**Alternative construct names**

Writes

**Related, but distinct construct names**

**Related terms**

*Monitors* : *Agent* monitors (“reads”) the value of the *attribute*.

**Language**

KAOS,  
<http://www2.info.ucl.ac.be/research/projects/AVL/ReqEng.html>

**Diagram type**

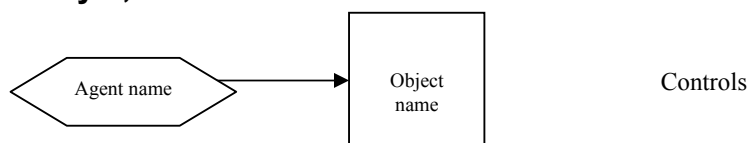
Agent model

### 2. Presentation

**Builds on**

**Built on by**

**Icon, line style, text**



## User-definable attributes

- **WhichAtt** : String = “”. indicate which attributes of the object are specifically controlled.

## Relations to other constructs

- Belongs to 1..1 agent model.
- 0:n [1:1], Object. *Object* is controlled by an *agent*.
- 0:n [1:1], Agent. *Agent* controls an *object*.

## Diagram layout conventions

## Other usage conventions

# 3. Representation

## Builds on

Agent  
Object

## Built on by

## Instantiation level

Instance and type level

## Classes of things

- 1:1 “*controlledObject*” **played by** *ComponentThing*.  
Represents *object*, controlled by an agent.
- 1:1 “*controllingAgent*” **played by** *ActiveComponentThing*.  
Represents the agent.

## Properties (and relationships)

- 1:1, “*theControls*” **played by** *BindingMutualProperty*.  
**Belongs to:** 1:1 [0:n], *controllingAgent*.  
Describing *controls* relationship.
- 1:n, “*explicitObjAttribute*” **played by** *AnyProperty*.  
**Belongs to:** *controlledObject*.  
**Sub-property of:** *theControls*.  
Defines explicitly which attribute of the object is controlled.
- 1:n, “*implicitObjAttribute*” **played by** *AnyProperty*.  
**Belongs to:** *controlledObject*.  
**Sub-property of:** *theControls*.  
Does not define explicitly which attribute of the object is controlled.

## Behaviour

Existence

## Modality (permission, recommendation etc)

Regular assertion

# 4. Open Issues

## KAOS : Domain property

<b>Document type:</b>	Working document
<b>Domain/Task/Topic:</b>	DEM / UEMML / Approaches
<b>Version:</b>	
<b>Date:</b>	2005.11.30
<b>Status:</b>	2 <sup>nd</sup> iteration
<b>Authors:</b>	Raimundas Matulevičius
<b>Distribution list:</b>	DEM
<b>Document history:</b>	

A *domain property* is a property that is naturally true about the composite system.

A *domain property* (*DomProp*) is a descriptive assertion about objects in the environment which holds independently of the software-to-be.

### 1. Preamble

#### Builds on

#### Built on by

Domain invariant. A *domain invariant* is a property known to hold in every state of some domain object. It is an indicative statement of domain knowledge.

Domain hypothesis. A *domain hypothesis* is a domain property about some domain object supposed to hold and used when arguing about the sufficient completeness of G-refinement.

#### Construct name

Domain property

#### Alternative construct names

A property that is naturally true about the composite system

A descriptive assertion about objects in the environment

#### Related, but distinct construct names

#### Related terms

- **Domain invariant** : a property known to hold in every state of some domain object
- **Domain hypothesis** : a property about some domain object supposed to hold and used when arguing about the sufficient completeness of goal refinements.

#### Language

KAOS,

<http://www2.info.ucl.ac.be/research/projects/AVL/ReqEng.html>

#### Diagram type

Goal model

Object model

## 2. Presentation

**Builds on**

**Built on by**

**Icon, line style, text**



Domain property

### User-definable attributes

[1:1], *Name* = "". A string allowing for unambiguous reference to corresponding instances at the application level.

[1:1], *Def*: FreeText = "". Free text used for precise, unambiguous definition of the corresponding instances at the application level.

[0:1], *FormalSpec*: KAOS real time temporal logic expression. Its values at the application level specify the corresponding *Def* attribute in the KAOS real-time temporal logic.

### Relations to other constructs

0:n [0:n], *subProperty*: goal. *Domain properties* refine the *goal* through the G-refinement relationship.

0:n [0:n], *isInDomain*: Conflict. *Conflicts* between goals are defined in a domain by domain properties.

### Diagram layout conventions

### Other usage conventions

## 3. Representation

**Builds on**

**Built on by**

**Instantiation level**

Instance level

### Classes of things

1:1 “*theDomainObject*” **played by** *CompositeThing*.

Describing object to which domain property belongs.

### Properties (and relationships)

1:1, “*theDomainProperty*” **played by** *Anything*.

**Belongs to:** *theDomainObject*.

Representing the domain property. *Domain property* is a property of an object.

1:1 [1:1], “*attributeName*” **played by** *AnyRegularProperty*.

**Sub-property:** *theDomainProperty*.

Represents *domain property* attribute *name*.

1:1 [1:1], “*attributeDef*” **played by** *AnyRegularProperty*.

**Sub-property:** *theDomainProperty*.

Represents *domain property* attribute *def*.

0:1 [1:1], “*attributeFormalSpec*” **played by** *AnyRegularProperty*.  
**Sub-property:** *theDomainProperty*.  
Represents *domain property* *attribute formalSpec*.

## Behaviour

Existence

## Modality (permission, recommendation etc)

Regular assertion

## 4. Open Issues



## KAOS : Environment agent

<b>Document type:</b>	Working document
<b>Domain/Task/Topic:</b>	DEM / UEMML / Approaches
<b>Version:</b>	
<b>Date:</b>	2005.11.30
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<b>Authors:</b>	Raimundas Matulevičius
<b>Distribution list:</b>	DEM
<b>Document history:</b>	

*Environment agent* (e.g., pre-existing software component, sensor, actuator, human, organizational unit, etc.)

### 1. Preamble

#### Builds on

Agent

#### Built on by

#### Construct name

Environment agent

#### Alternative construct names

#### Related, but distinct construct names

#### Related terms

- *Agents* : active objects capable of performing operations.
- *Software agent* : an agent in the system-to-be.

#### Language

KAOS,  
<http://www2.info.ucl.ac.be/research/projects/AVL/ReqEng.html>

#### Diagram type

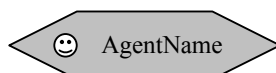
Agent model

### 2. Presentation

#### Builds on

#### Built on by

#### Icon, line style, text



Environment agent

#### User-definable attributes



## Relations to other constructs

### Diagram layout conventions

### Other usage conventions

## 3. Representation

### Builds on

### Built on by

### Instantiation level

Type level

### Classes of things

1:1, “*isEnvironmentAgent*” **played by** *ActiveComponentThing*.

*Environment agents* are *agents* and inherits all agent attributes and properties.

### Properties (and relationships)

### Behaviour

Existence

### Modality (permission, recommendation etc)

Regular assertion

## 4. Open Issues

## KAOS : Event

<b>Document type:</b>	Working document
<b>Domain/Task/Topic:</b>	DEM / UEMML / Approaches
<b>Version:</b>	
<b>Date:</b>	2005.11.30
<b>Status:</b>	2 <sup>nd</sup> iteration
<b>Authors:</b>	Raimundas Matulevičius
<b>Distribution list:</b>	DEM
<b>Document history:</b>	

*Event* is an instantaneous object.

### 1. Preamble

#### Builds on

Object

#### Built on by

#### Construct name

Event

#### Alternative construct names

An instantaneous object

#### Related, but distinct construct names

#### Related terms

Object

#### Language

KAOS,  
<http://www2.info.ucl.ac.be/research/projects/AVL/ReqEng.html>

#### Diagram type

Object model  
Operation model

### 2. Presentation

#### Builds on

#### Built on by

#### Icon, line style, text



Event

## User-definable attributes

Event inherits all the attributes of the object.

## Relations to other constructs

Event inherits all the relationships of the object.

1:1 [1:n], *occurs* : operation. The applications of an *operation* may be caused by *event(s)*.

## Diagram layout conventions

## Other usage conventions

# 3. Representation

## Builds on

## Built on by

## Instantiation level

Instance level

## Classes of things

1:1, “*theEvent*” **played by** *ChangingThing*.  
Describing the *event*.

## Properties (and relationships)

## Behaviour

Event

### REPRESENTED STATE ENTRIES

“*initialState*” **played by** *StateOfAThing*

**State constraints:** State constraints are defined by object implicit and explicit attributes (inputs to the *operation*).

“*resultState*” **played by** *StateOfAThing*

**State constraints:** State constraints are defined by object implicit and explicit attributes (outputs from the *operation*).

### REPRESENTED EVENT ENTRIES

“*occur*” **played by** *EventInAThing*

**From state:** *initialState*

**To state:** *resultState*

**Trigger:** *reqTrig* sub-property of *operationalisation*.

**Condition:** *reqPre* and *reqPost* in *operationalisation* and *domPre* and *domPost* in *operation*.

**Action:** when event occurs the *operation* is caused.

## Modality (permission, recommendation etc)

Regular assertion

# 4. Open Issues

TBF – A *goal* defines a set of admissible histories in the composed system. Intuitively, a history is a temporal sequence of states of the system. Specify *Scenario*, *Snapshot*, *Interaction*, *Source*, *Target*, and *State transition* constraints. This is related to *Agent*, *Event*, and *Operation* constraints.

## KAOS : Expectation

<b>Document type:</b>	Working document
<b>Domain/Task/Topic:</b>	DEM / UEMML / Approaches
<b>Version:</b>	
<b>Date:</b>	2005.11.30
<b>Status:</b>	2 <sup>nd</sup> iteration
<b>Authors:</b>	Raimundas Matulevičius
<b>Distribution list:</b>	DEM
<b>Document history:</b>	

An *expectation* is a *goal* assigned to an *environment agent*.

### 1. Preamble

#### Builds on

Goal

#### Built on by

#### Construct name

Expectation

#### Alternative construct names

Assumption

#### Related, but distinct construct names

*Terminal goal*: goal which has no G-requirement.

#### Related terms

*Requirement*: a goal assigned to an agent in the software-to-be.

*Softgoal*: a goal that cannot be said to be satisfied in a clearcut sense.

**Comment**: can an expectation be a softgoal?

*Maintain goal*: a goal requiring that some property always holds.

*Avoid goal*: a goal requiring that some property never holds.

*Achieve goal*: a goal requiring that some property eventually hold.

*Cease goal*: a goal requiring that some property eventually stops to hold.

#### Language

KAOS,

<http://www2.info.ucl.ac.be/research/projects/AVL/ReqEng.html>

#### Diagram type

Goal model

## 2. Presentation

**Builds on**

**Built on by**

**Icon, line style, text**



Expectation

### User-definable attributes

Requirement inherits all the attributes of the goal.

### Relations to other constructs

- Belongs 1:1 to goal model.
- 1:n [1:n], *responsible : environment agent*. *Expectation* is assigned through responsibility relationship to an *environment agent*.

### Diagram layout conventions

### Other usage conventions

## 3. Representation

**Builds on**

**Comment:** *Expectation* is a goal and has most of the goal classes and properties. But *expectation* is also a terminal goal, so it has no G-refinement.

**Built on by**

**Instantiation level**

Instance level

**Comment:** Can we have classes of environment agents and these classes or individual expectations assigned?

### Classes of things

1:1, “*environmentAgent*” **played by** *ActiveComponentThing*.  
Describing the agent an *expectation* is assigned.

### Properties (and relationships)

1:1, “*theExpectation*” **played by** *ComplexStateLaw*.

**Belongs to:** 0:1 [0:n] *environmentAgent*.

**Belongs to:** 0:1 [1:1] *goalOwner*.

**State law:** Is restricted by the assignment relationship. An expectation himself restricts state of the concerned object.

Representing the *expectation*. Expectation as a goal, has a goal owner.

1:1, “*isTerminalGoal*” **played by** *StateLaw*.

**Sub-property:** 1:1 [1:1], *theExpectation*.

**State law:**  $\forall g \in \text{Goal}, \forall a \in \text{Assignment}, a.\text{assignedGoal} = g$

$\Rightarrow \neg \exists \text{ gr} \in \text{G-refinement: gr.superGoal} = \text{g}$

*Expectation* is a terminal *goal* which means that an *expectation* can not have G-refinement.

## Behaviour

Existence

## Modality (permission, recommendation etc)

**Intention** of a goal owner;

**Obligation** of an *environment agent*.

## 4. Open Issues



## KAOS : Goal

<b>Document type:</b>	Working document
<b>Domain/Task/Topic:</b>	DEM / UEMML / Approaches
<b>Version:</b>	
<b>Date:</b>	2005.11.30
<b>Status:</b>	2 <sup>nd</sup> iteration
<b>Authors:</b>	Raimundas Matulevičius
<b>Distribution list:</b>	DEM
<b>Document history:</b>	

A *goal* is a prescriptive assertion capturing some objective to be met by cooperation of agents from the agent model. A *goal* prescribes a set of desired behaviours. A *goal* defines an objective the composite system should meet usually through the cooperation of multiple agents.

### 1. Preamble

#### Builds on

#### Built on by

softgoal  
maintain goal  
achieve goal  
cease goal  
avoid goal  
requirement  
expectation (assumption)

**Comment:** All the mentioned constructs are goals having additional features to the ones defined in this template.

#### Construct name

Goal

#### Alternative construct names

a prescriptive assertion  
a set of desirable behaviours  
an objective a desirable system should meet  
a sub-goal  
a parent goal  
a super goal

#### Related, but distinct construct names

#### Related terms

*Softgoal*: goal that do not have a clear-cut criterion for their satisfaction.  
*Maintain goal*: a goal requiring that some property always holds.  
*Avoid goal*: a goal requiring that some property never holds.  
*Achieve goal*: a goal requiring that some property eventually hold.  
*Cease goal*: a goal requiring that some property eventually stops to hold.  
*Terminal goals*: a goal which has no G-refinement.  
*Requirement*: a goal assigned to an agent in the software to be.  
*Expectation (assumption)*: a goal assigned to an agent in the environment.



## Language

KAOS, <http://www2.info.ucl.ac.be/research/projects/AVL/ReqEng.html>

## Diagram type

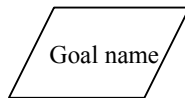
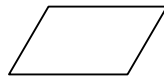
Goal model

## 2. Presentation

### Builds on

### Built on by

### Icon, line style, text



Goal

### User-definable attributes

- [1:1] *Name*: String. A string allowing for unambiguous reference to a corresponding goal at the application level.
  - [1:1] *Def*: String. Free text used for precise, unambiguous definition of the goal at the application level.
  - [0:1] *FormalSpec*: KRTTL. Its values at the application level specify the corresponding *Def* attribute in the KAOS real-time temporal logic.
  - [0:1] *Priority*: PriorityType. Values at the application level specify the extent to which the goal is mandatory or optional.
  - [0:1] *Owner*: String. Defines stakeholder which identified and argued for that goal.
  - [0:1] *Category*: set\_of Strings {*satisfaction*, *safety*, *security*, *information*, *accuracy*, and others}. Category provides a classification of goals that can be used to guide the acquisition, definition and refinement.
- Any other attributes that the user wished to add.

### Relations to other constructs

Belongs 1:1 to Goal model.

- 0:n [1:1] *assignedGoal* : assignment. Defines relationship between *goal* and *assignment*.
- 0:n [0:n] *concerns* : object. *Goal* definition refers to the *objects* and their *attributes*.
- 1:1 [0:n] *superGoal* : goal. *Goal* is a super (parent) goal in the *G-refinement* relationship.
- 0:n [1:n] *subGoal* : goal. *Goal* refines a super (parent) goal through the *G-refinement* relationship.
- 0:n [0:n] *subProperty* : domain properties. Super (parent) *goals* are refined to a *subgoal* and *domain properties* through the *G-refinement* relationship.
- 0:n [1:1] *op\_goal* : operationalisation. *Operationalisation* defines *operations* which operationalise this goal through required conditions (*reqPre*, *reqTrig*, and *reqPost*).
- 0:n [2:n] *betweenGoals* : conflict. One or several *goals* could be part of the conflict when *boundary condition* is determined.

## Diagram layout conventions

## Other usage conventions

# 3. Representation

## Builds on

## Built on by

*Assignment* – defines how *goals* can be assigned to *agents*.  
*Operationalisation* – defines how *goals* are operationalised.  
*G-refinement* – defines how *goals* are refined.  
*Conflict* – defines the way *conflicts* between *goals* are represented.

## Instantiation level

Both type and instance level

## Classes of things

- 1:1, “*concernedObject*” **played by** *AllThing*.  
Describing *object* concerned by a *goal*.
- 1:1, “*goalOwner*” **played by** *StakeholderThing*.  
Describing *goal owner* which holds the goal. Class *StakeholderThing* has a characteristic *holds goal*.  
*StakeholderThing* is subclass of the *BWW-HumanThing*.

## Properties (and relationships)

- 1:1, “*theGoal*” **played by** *ComplexLawProperty*.  
**Belongs to:** 0:1 [1:1] *goalOwner*.  
**Law:** goal restricts state of the object by concerning it.  
Representing the goal which is held by a goal owner.
- 1:n [1:n], “*concExplicitObjAttribute*” **played by** *AnyProperty*.  
**Belongs to:** 0:n [0:n], *concernedObject*.  
**Sub-property:** *theGoal*.  
**Sub-property:** *attributeDef*.  
**Sub-property:** *attributeFormalSpec*.  
A goal concerns an *object*’s *attribute*.
- 1:n [1:n], “*concImplicitObjAttribute*” **played by** *AnyProperty*.  
**Belongs to:** 0:n [0:n], *concernedObject*.  
**Sub-property:** *theGoal*.  
**Sub-property:** *attributeDef*.  
**Sub-property:** *attributeFormalSpec*.  
A goal concerns an *object*, without defining the concrete *attribute* of the concern.
- 1:1 [1:1], “*attributeName*” **played by** *AnyRegularProperty*.  
**Sub-property:** *theGoal*.  
Represents *goal* attribute *name*.
- 1:1 [1:1], “*attributeDef*” **played by** *AnyRegularProperty*.  
**Sub-property:** *theGoal*.  
Represents *goal* attribute *def*.
- 0:1 [1:1], “*attributeFormalSpec*” **played by** *AnyRegularProperty*.  
**Sub-property:** *theGoal*.  
Represents *goal* attribute *formalSpec*.

0:1 [1:1], “*attributePriority*” **played by** *AnyRegularProperty*.

**Sub-property:** *theGoal*.

Represents *goal* attribute *priority*.

0:1 [1:1], “*attributeCategory*” **played by** *AnyRegularProperty*.

**Sub-property:** *theGoal*.

Represents *goal* attribute *category*.

## Behaviour

Existence

## Modality (permission, recommendation etc)

Intention of a goal owner;

Obligation of an *agent*.

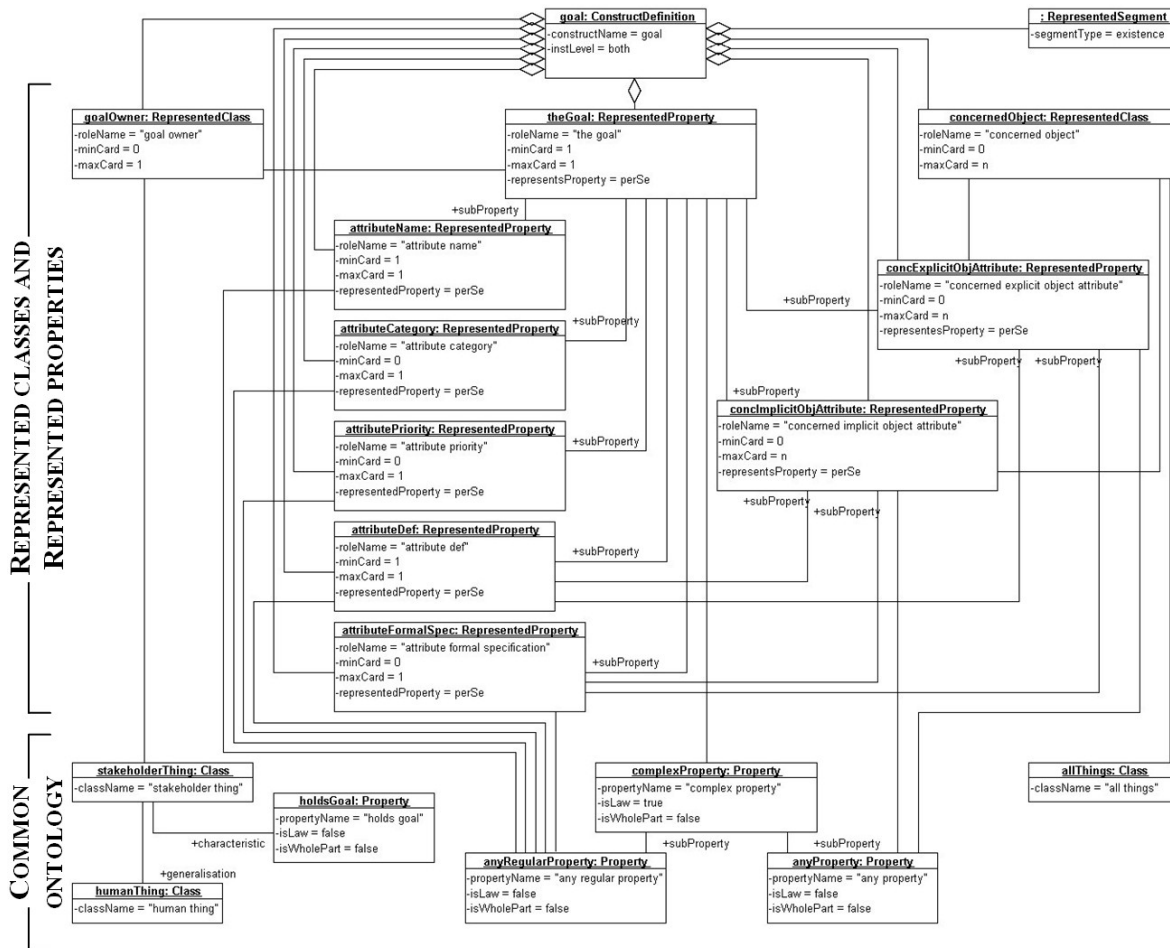
## 4. Open Issues

In this template it is not considered:

*Obstacle* constructs and relationship with a goal.

*Dependency* constructs between agents both through goal and/or through operation.

*History* (and its constructs) in a composed system.



## KAOS : Goal refinement

<b>Document type:</b>	Working document
<b>Domain/Task/Topic:</b>	DEM / UEMML / Approaches
<b>Version:</b>	
<b>Date:</b>	2005.11.30
<b>Status:</b>	2 <sup>nd</sup> iteration
<b>Authors:</b>	Raimundas Matulevičius
<b>Distribution list:</b>	DEM
<b>Document history:</b>	

Goals refinement is a relationship which is used to refine *goals* to *subgoals* and to *domain properties*. Parent *goal* could have alternative refinements.

### 1. Preamble

#### Builds on

OR-refinement  
AND-refinement

#### Built on by

#### Construct name

Goal refinement

#### Alternative construct names

Refines  
G-refinement

#### Related, but distinct construct names

#### Related terms

#### Language

KAOS,  
<http://www2.info.ucl.ac.be/research/projects/AVL/ReqEng.html>

#### Diagram type

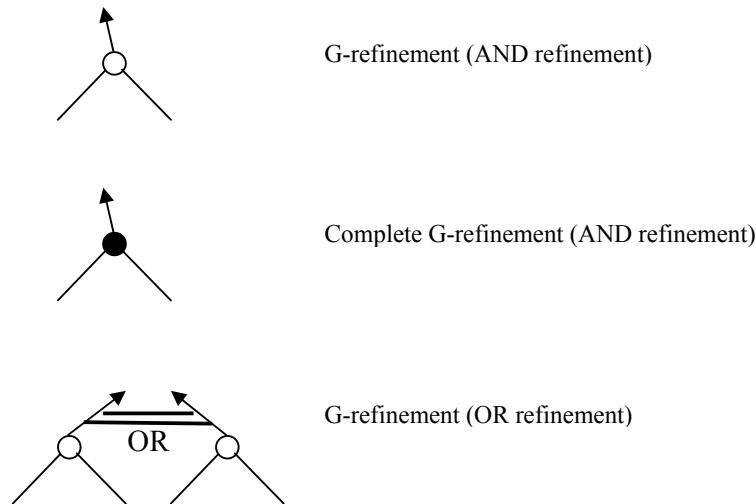
Goal model

### 2. Presentation

#### Builds on

#### Built on by

## Icon, line style, text



## User-definable attributes

[1:1] *Complete*: Boolean. Indicate whether the refinement is *arguably sufficient* (value "complete") or not arguably sufficient (value "undetermined") to satisfy the parent goal.

[0:1] *Tactics*: set\_of{IntroduceMileston, DecomposeAntecedentByCase, IntroduceAccuracyGoal} document the tactics used for refining the parent goal. Values include IntroduceMileston, DecomposeAntecedentByCase, IntroduceAccuracyGoal.

[0:1] *AltName*: String ="". To name the corresponding alternative for further reference. In case a goal is refined into multiple alternative G-refinements this meta-attribute is mandatory.

## Relations to other constructs

- Belongs to 1..1 Goal model.
- 1:1 [1:1], Goal. *G-refinement* is used to refine a parent *goal*.
- 1:n [1:1], Goal. *G-refinement* refines parent goal to several *subgoals*.
- 1:n [1:1], Domain property. *G-refinement* refines parent goal to subgoals and *domain properties*.

## Diagram layout conventions

## Other usage conventions

## 3. Representation

### Builds on

Goal

### Built on by

Domain property

### Instantiation level

Instance and type levels

### Classes of things

1:1, "goalOwner" **played by** *StakeholderThing*.

Describing *goal owner* which holds the goal. Class *StakeholderThing* has a characteristic *holds goal*.

*StakeholderThing* is subclass of the *BWW-HumanThing* (specified in *goal* template).

G-refinement is a mutual relationtion between goal owners.

1:1, “*concernedObject*” **played by** *ComponentThing*.

Describing *object* concerned by a *goal*. This object is characterised by a *domain properties* – either domain invariant or domain hypothesis.

## Properties (and relationships)

1:1, “*theGoal*” **played by** *ComplexLawProperty*.

**Belongs to:** 0:1 [1:1], *goalOwner*.

**Law:** restricts the the possible values of the *object* attributes.

Representing the goal which is held by a goal owner.

1:1 [0:n], *superGoal* **played by** *ComplexLawProperty*.

**Sub-property:** 0:1 [1:1] *theGoal*.

Supergoal is refined by the subgoals. Like a goal, it is complex (has attributes) and law property (has restrictions over the concerned object –see goal template).

1:n [0:n], *subGoal* **played by** *ComplexLawProperty*.

**Sub-property:** 1:1 [1:1] *theGoal*.

Subgoals refine the super goal. Like goals they are complex (have attributes) and law properties (have restrictions over the concerned object –see goal template).

0:n [0:n], *domainHypothesis* **played by** *AnyProperty*.

A *domain hypothesis* is a domain property about some domain object supposed to hold and used when arguing about the sufficient completeness of G-refinement.

**Also represented by:** *domain property*.

0:n [0:n], *domainInvariant* **played by** *AnyProperty*.

A *domain invariant* is a property known to hold in every state of some domain object. It is an indicative statement of domain knowledge.

**Also represented by:** *domain property*.

1:1, “*theG-Refinement*” **played by** *ComplexMutualProperty*.

**Type:** *AND/OR relationship*.

**Sub-property:** 0:n [1:1] *domainHypothesis*.

**Sub-property:** 0:n [1:1] *domainInvariant*.

**Sub-property:** 1:1 [1:1] *superGoal*.

**Sub-property:** 0:n [1:1] *subGoal*

Describing *goal refinement*.

1:1 [1:1], “*attributeComplete*” **played by** *AnyRegularProperty*.

**Sub-property:** *theG-Refinement*.

Represents *G-refinement* attribute *complete*.

0:1 [1:1], “*attributeAltName*” **played by** *AnyRegularProperty*.

**Sub-property:** *theG-Refinement*.

Represents *G-refinement* attribute *altName*.

0:1 [1:1], “*attributeTactics*” **played by** *AnyRegularProperty*.

**Sub-property:** *theG-Refinement*.

Represents *G-refinement* attribute *tactics*.

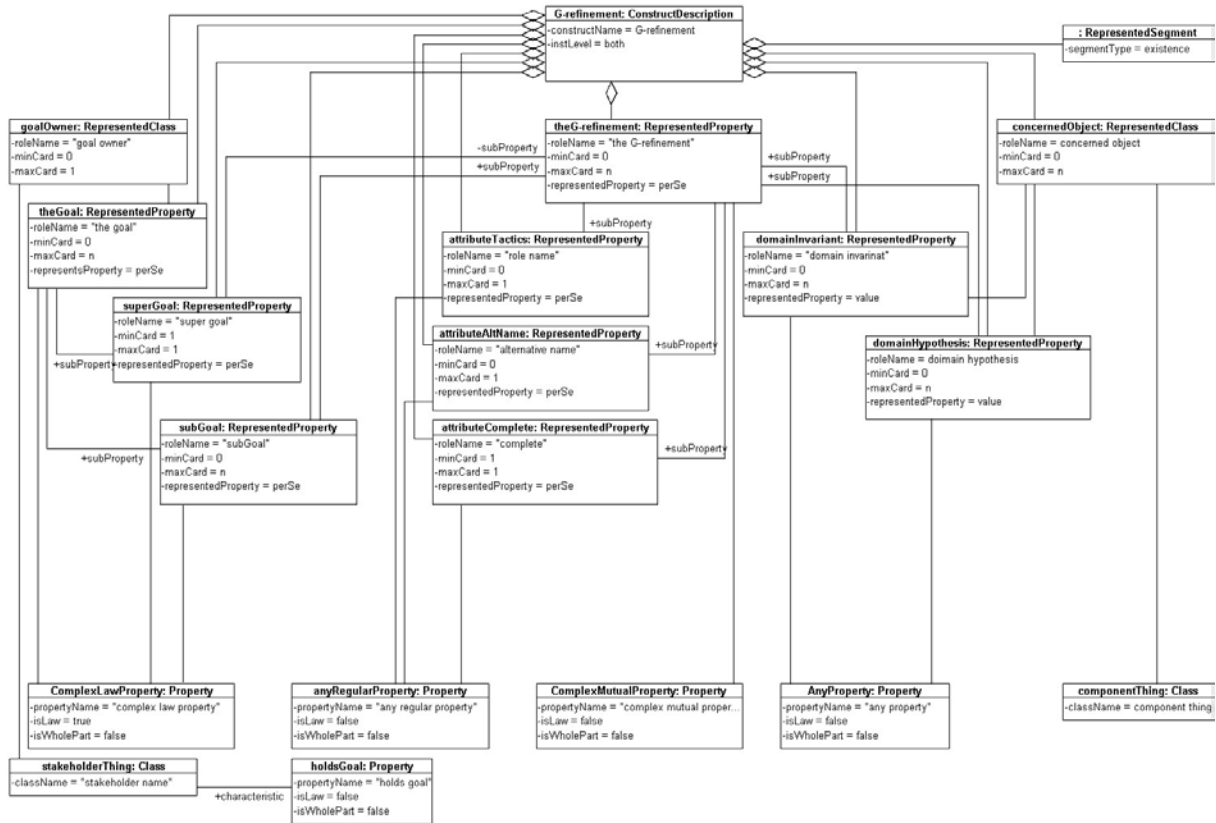
## Behaviour

Existence

## Modality (permission, recommendation etc)

Regular assertion

## 4. Open Issues



## KAOS : Input

<b>Document type:</b>	Working document
<b>Domain/Task/Topic:</b>	DEM / UEMML / Approaches
<b>Version:</b>	
<b>Date:</b>	2005.11.30
<b>Status:</b>	2 <sup>nd</sup> iteration
<b>Authors:</b>	Raimundas Matulevičius
<b>Distribution list:</b>	DEM
<b>Document history:</b>	

An object is among the *inputs* of an operation if it is among the sorts making up the domain of the relation defined by the operation.

### 1. Preamble

**Builds on**

**Built on by**

**Construct name**

Inputs

**Alternative construct names**

**Related, but distinct construct names**

**Related terms**

*Outputs* : An object is among the *outputs* of an operation if it is among the sorts making up the co-domain of the relation defined by the operation.

**Language**

KAOS,  
<http://www2.info.ucl.ac.be/research/projects/AVL/ReqEng.html>

**Diagram type**

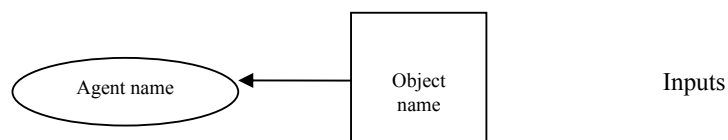
Operation model

### 2. Presentation

**Builds on**

**Built on by**

**Icon, line style, text**





## User-definable attributes

[0:1] *WhichAtt* : String = “”. Indicate which attributes of the object are specifically taken as input of the operation.

## Relations to other constructs

- Belongs to 1..1 operation model.
- 0:n [1:1], Object. *Object* is input to an *operation*.
- 0:n [1:1], Operation. *Operation* has input an *object*.

## Diagram layout conventions

## Other usage conventions

# 3. Representation

## Builds on

## Built on by

## Instantiation level

Type level

## Classes of things

1:1 “*inObject*” **played by** *ComponentThing*.  
Represents *object*, which is input to operation.

0:n, “*causingEvent*” **played by** *ChangingThing*.

## Properties (and relationships)

1:1, “*theInput*” **played by** *BindingMutualProperty*.

**Belongs to:** 0:n [1:1], *inObject*.

Describing *input*. Input is a binding mutual property between the event which causes the operation and the object which is input to this operation.

1:n, “*explicitObjAttribute*” **played by** *AnyProperty*.

**Belongs to:** *inObject*.

**Sub-property of:** *theInput*.

Defines explicitly which attribute of the object is an input.

1:n, “*implicitObjAttribute*” **played by** *AnyProperty*.

**Belongs to:** *inObject*.

**Sub-property of:** *theInput*.

Does not define explicitly which attribute of the object is an input.

0:1, “*attributeWhichAtt*” **played by** *AnyRegularProperty*.

**Sub-property:** *theInput*.

Representing the *input* attribute *whichAtt*.

0:n [1:1], “*forOperation*” **played by** *TransformationLaw*.

**Belongs to:** *causingEvent*.

**Sub-property:** *theInput*.

**Transformation law:** operation gets input.

Describing the operation which has input.

**Also represented by** *operation*.

## **Behaviour**

Existence

## **Modality (permission, recommendation etc)**

Regular assertion

## **4. Open Issues**



## KAOS : Maintain goal

<b>Document type:</b>	Working document
<b>Domain/Task/Topic:</b>	DEM / UEMML / Approaches
<b>Version:</b>	
<b>Date:</b>	2005.11.30
<b>Status:</b>	2 <sup>nd</sup> iteration
<b>Authors:</b>	Raimundas Matulevičius
<b>Distribution list:</b>	DEM
<b>Document history:</b>	

*Maintain goals* are goals requiring that some property always holds

*Maintain goals* state that some target condition on system states should always hold under some current condition.

### 1. Preamble

#### Builds on

Goal

#### Built on by

#### Construct name

Maintain goal

#### Alternative construct names

goal, requiring that some property always holds

#### Related, but distinct construct names

goal with a pattern maintain

#### Related terms

*Goal* : a prescriptive assertion capturing some objective to be met by cooperation of agents from the agent model.

*Cease goal*: a goal requiring that some property eventually stops to hold.

*Achieve goal*: a goal requiring that some property eventually hold.

*Avoid goal*: a goal requiring that some property never holds.

*Softgoal*: goal that do not have a clear-cut criterion for their satisfaction.

*Terminal goals*: a goal which has no G-refinement.

*Requirement*: a goal assigned to an agent in the software to be.

*Expectation (assumption)*: a goal assigned to an agent in the environment.

**Comment:** Can a goal with a pattern be softgoal, terminal goal (requirement and expectation)?

#### Language

KAOS, <http://www2.info.ucl.ac.be/research/projects/AVL/ReqEng.html>

#### Diagram type

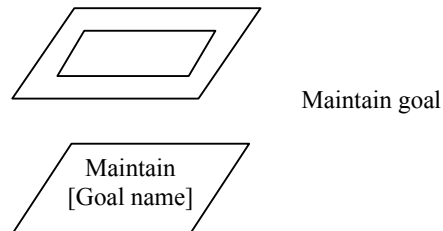
Goal model

## 2. Presentation

**Builds on**

**Built on by**

**Icon, line style, text**



**User-definable attributes**

**Relations to other constructs**

**Diagram layout conventions**

**Other usage conventions**

## 3. Representation

**Builds on**

**Built on by**

**Instantiation level**

Both type and instance level

### Classes of things

1:1, “*goalOwner*” **played by** *StakeholderThing*.

Describing *goal owner* which holds the goal. Class *StakeholderThing* has a characteristic *holds goal*.  
*StakeholderThing* is subclass of the *BWW-HumanThing*.

1:1, “*concernedObject*” **played by** *AllThing*.

Describing *object* concerned by a goal.

**Comment:** *Maintain goal* has the same classes as a *goal*. It belongs to a *goal owner* and has the sub-properties. These classes are described here as they are used in property definition.

### Properties (and relationships)

1:1, “*theMaintainGoal*” **played by** *ComplexStateLaw*.

**Belongs to:** 0:1 [1:1], *goalOwner*.

**State law:** indicates states that cannot be in concerned object.

Representing the maintain goal which is held by a goal owner and requires that some properties of the concerned object always holds.

**Comment:** For more *avoid goal* properties (such as *concExplicitObjAttribute*, *concImplicitObjAttribute*, *attributeName*, *attributeDef*, *attributeFormalSpec*, *attributePriority*, and *attributeCategory*), see *goal*.

## **Behaviour**

Existence

## **Modality (permission, recommendation etc)**

Intention of a goal owner;

## **4. Open Issues**

## **Change List**



## KAOS : Monitor

<b>Document type:</b>	Working document
<b>Domain/Task/Topic:</b>	DEM / UEMML / Approaches
<b>Version:</b>	
<b>Date:</b>	2005.11.30
<b>Status:</b>	2 <sup>nd</sup> iteration
<b>Authors:</b>	Raimundas Matulevičius
<b>Distribution list:</b>	DEM
<b>Document history:</b>	

*Agent* monitors (“reads”) the value of the *attribute*.

### 1. Preamble

**Builds on**

**Built on by**

**Construct name**

Monitors

**Alternative construct names**

Reads

**Related, but distinct construct names**

**Related terms**

*Controls* : *agent* controls (“writes”) the value of the *object* attribute.

**Language**

KAOS,  
<http://www2.info.ucl.ac.be/research/projects/AVL/ReqEng.html>

**Diagram type**

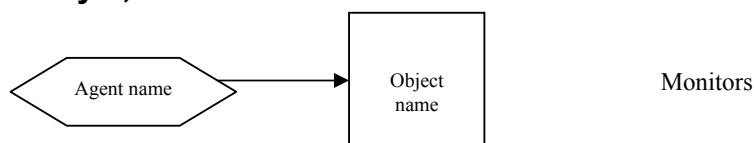
Agent model

### 2. Presentation

**Builds on**

**Built on by**

**Icon, line style, text**



**User-definable attributes**

- *WhichAtt* : String = “”. indicate which attributes of the object are specifically monitored.



## Relations to other constructs

- 0:n [1:1], Object. *Object* is monitored by an *agent*.
- 0:n [1:1], Agent. *Agent* monitors an *object*.

## Diagram layout conventions

## Other usage conventions

# 3. Representation

## Builds on

## Built on by

## Instantiation level

Instance level

## Classes of things

- 1:1 “*monitoredObject*” **played by** *ComponentThing*.  
Represents *object*, monitored by agent.
- 1:1 “*monitoringAgent*” **played by** *ActiveComponentThing*.  
Represents the agent.

## Properties (and relationships)

- 1:1, “*theMonitors*” **played by** *BindingMutualProperty*.  
**Belongs to:** 1:1 [0:n], *monitoringAgent*.  
Describing *monitors* relationship.
- 1:n, “*explicitObjAttribute*” **played by** *AnyProperty*.  
**Belongs to:** *monitoredObject*.  
**Sub-property of:** *theMonitors*.  
Defines explicitly which attribute of the object is monitored.
- 1:n, “*implicitObjAttribute*” **played by** *AnyProperty*.  
**Belongs to:** *monitoredObject*.  
**Sub-property of:** *theMonitors*.  
Does not define explicitly which attribute of the object is monitored.

## Behaviour

Existence

## Modality (permission, recommendation etc)

Regular assertion

# 4. Open Issues

## KAOS : Object

<b>Document type:</b>	Working document
<b>Domain/Task/Topic:</b>	DEM / UEML / Approaches
<b>Version:</b>	
<b>Date:</b>	2005.11.30
<b>Status:</b>	2 <sup>nd</sup> iteration
<b>Authors:</b>	Raimundas Matulevičius
<b>Distribution list:</b>	DEM
<b>Document history:</b>	

An *object* is a thing of interest in the system being modeled whose instances can be distinctly identified and may evolve from state to state.

An *object* instance is a thing that can be distinctly identified. A domain-level object describes a set of such instances that share some common characteristics.

### 1. Preamble

#### Builds on

#### Built on by

#### Construct name

Object

#### Alternative construct names

a thing of interest

a thing that can be distinctly identified

#### Related, but distinct construct names

#### Related terms

Agent

Entity

Event

Relationship

#### Language

KAOS,

<http://www2.info.ucl.ac.be/research/projects/AVL/ReqEng.html>

#### Diagram type

Object model

### 2. Presentation

#### Builds on

## Built on by

## Icon, line style, text

## User-definable attributes

[1:1] *Name* : String = "" . A string allowing for unambiguous reference to corresponding instances at the application level. The *name* of the object is used to identify the object.

[1:1] *Def* : Text = "" . Tree text used for precise, unambiguous definition of the corresponding instances at the application level. The *definition* of an object is a natural language statement that should provide a precise interpretation for the set member(*Obj*), so that one can tell whether or not a particular object instance is currently an instance of the domain-level object.

[0:1] *Alive* : Boolean = "True/False" . Value in some state at the instance level indicates whether or not the corresponding object instance *exists* in that state, that is, has appeared in the system without disappearing yet.

## Relations to other constructs

- Belongs 1:1 to object model.
- 0:n [0:n], *concerns* : goal. Goals *concern* objects - this means that their formulation in Def refers to these objects and their attributes.
- 1:n [0:n], *input* : operation. *Operations* are related to *objects* through *input* links.
- 1:n [0:n], *output* : operation. *Operations* are related to *objects* through *output* links.
- 0:n [0:n], *monitors* : agent. An *agent* monitors an *object* if the states of the object are directly observable by it.
- 0:n [0:n], *controls* : agent. An *agent* controls an *object* if the states of the object are directly controllable by it.

## Diagram layout conventions

## Other usage conventions

# 3. Representation

## Builds on

## Built on by

## Instantiation level

Both type and instance level

## Classes of things

1:1, "*theObject*" played by *ComponentThing*.

## Properties (and relationships)

1:1 [1:1], "*attributeName*" played by *AnyRegularProperty*.

**Sub-property:** *theGoal*.

Represents *goal* attribute *name*.

1:1 [1:1], "*attributeDef*" played by *AnyRegularProperty*.

**Sub-property:** *theGoal*.

Represents *goal* attribute *def*.

## Behaviour

Existence

## Modality (permission, recommendation etc)

Regular assertion

## 4. Open Issues



## KAOS : Operation

<b>Document type:</b>	Working document
<b>Domain/Task/Topic:</b>	DEM / UEMML / Approaches
<b>Version:</b>	
<b>Date:</b>	2005.11.30
<b>Status:</b>	2 <sup>nd</sup> iteration
<b>Authors:</b>	Raimundas Matulevičius
<b>Distribution list:</b>	DEM
<b>Document history:</b>	

An *operation* is an input-output relation over *objects*; operation applications define state transitions. *Operations* are characterized by pre-, post-, and trigger conditions. A distinction is made between *domain* pre-/post- conditions, which capture the elementary state transitions defined by *operation* applications in the domain, and *required* pre/trigger/postconditions, which capture additional strengthening to ensure that the goals are met.

### 1. Preamble

**Builds on**

**Built on by**

**Construct name**

Operation

**Alternative construct names**

An input-output relation

**Related, but distinct construct names**

**Related terms**

**Language**

KAOS,  
<http://www2.info.ucl.ac.be/research/projects/AVL/ReqEng.html>

**Diagram type**

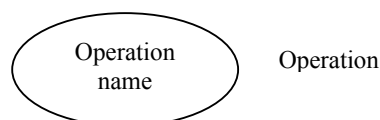
Operation model

### 2. Presentation

**Builds on**

**Built on by**

**Icon, line style, text**



## User-definable attributes

- [1:1] *Name*: String = "". A string allowing for unambiguous reference to corresponding instances at the application level.
- [1:1] *Def*: FreeText = "". Free text used for precise, unambiguous definition of the corresponding instances at the application level.
- [0:1] *modifier*: Boolean. Indicate whether the operation is an object *Modifier* or *Observer*.

## Relations to other constructs

Belongs 1:1 to goal model.

- 1:1 [0:n] **operationalise** : goal. *Goals* assigned to agents are *operationalised* through *operations*. The operationalisation of a goal through some operation entails permissions and obligations on the operation's applications; the latter are captured by the *ReqPre*, *ReqPost* and *ReqTrig* metaattributes of the *Operationalisation* relationship that strengthen the operation's *domain pre/postconditions*.
- 0:n [1:n] **input** : object. *Operations* are related to *objects* through input links.
- 0:n [1:n] **output** : object. *Operations* are related to *objects* through output links.
- 1:n [1:1] **occurs** : event. The applications of an *operation* may be caused by *event(s)*. This means that the *operation's* *ReqTrig* includes a predicate *occurs* on instances of that *event*.
- 1:n [1:n] **performs** : agent. A meta-model constraint requires any agent *Responsible* for some goal to *Perform* all the operations that *Operationalize* that goal in accordance with the permissions and obligations specified in the operation's *ReqPre*, *ReqTrig* and *ReqPost* conditions. The *Performance* meta-relationship is thus a derived one.

## Diagram layout conventions

### Other usage conventions

## 3. Representation

### Builds on

### Built on by

### Instantiation level

Type level

### Classes of things

- 1:n, "causingEvent" **played by** *ChangingThing*.  
Operation is caused by event(s).
- 1:1, "op\_object" **played by** *ComponentThing*.  
Operation gets input from and makes output to the object.

### Properties (and relationships)

- 0:n [0:n] "inputForOperation" **played by** *BindingMutualProperty*.  
**Belongs to:** *op\_object*.  
Describing input for operation.  
**Also represented by:** *Inputs*.
- 0:n [0:n] "outputForOperation" **played by** *BindingMutualProperty*.  
**Belongs to:** *op\_object*.  
Describing output for operation.  
**Also represented by:** *Outputs*.
- 1:1, "theOperation" **played by** *TransformationLaw*.  
**Belongs to:** *causingEvent*.  
**Sub-property of:** *inputForOperation*.

**Sub-property of:** *outputFromOperation*.

**Transformation law:** operation is performed by an agent responsible for the goal fulfilment. Whenever the required conditions hold, performing the operations satisfies the goal.  
Representing the operation.

1:1, “*attributeName*” **played by** *AnyRegularProperty*.

**Sub-property of:** *theOperation*.

Represents *operation* attribute *name*.

1:1, “*attributeDef*” **played by** *AnyRegularProperty*.

**Sub-property of:** *theOperation*.

Represents *operation* attribute *altName*.

0:1, “*modifier*” **played by** *AnyRegularProperty*.

**Sub-property of:** *theOperation*.

Represents *operation* attribute *altName*.

1:1 [1:1] “*domPre*” **played by** *StateLaw*.

**Sub-property of:** 1:1 [1:1] *operation*.

Characterising the states before any application of the operation;

1:1 [1:1] “*domPost*” **played by** *StateLaw*.

**Sub-property of:** 1:1 [1:1] *operation*.

Defining a relation between states before and after applications of the operation;

## Behaviour

Process

### REPRESENTED STATE ENTRIES

“*initState*” **played by** *StateOfAThing*,

**Defining property:** *inputForOperation*.

**State constraint:** *implicit and explicit attribute of an object*.

“*resultState*” **played by** *StateOfAThing*,

**Defining property:** *outputForOperation*

**state constraint:** *implicit and explicit attributes of an object*.

### REPRESENTED EVENT ENTRIES

“*eventOccurs*” **played by** *ExternalEvent*,

**From state:** *initState*

**To state:** *initState*

**Trigger:** *reqTrig* sub-property of *operationalisation*.

**Condition:** *reqPre* (sub-property of *operationalisation*) and *domPre* (sub-property of *operation*) holds.

**Action:** operation is initiated,

**effected by** *Event*.

“*getInput*” **played by** *InternalEvent*,

**From state:** *initState*

**To state:** *initState*

**Trigger:** *reqTrig* sub-property of *operationalisation*.

**Condition:** *reqPre* (sub-property of *operationalisation*) and *domPre* (sub-property of *operation*) holds.

*reqPost* (sub-property of *operationalisation*) and *domPost* (sub-property of *operation*) introduced.

**Action:** object implicit and explicit attributes are taken as the input for the operation.

“*setOutput*” **played by** *InternalEvent*,

**From state:** *initState*

**To state:** *resultState*

**Trigger:** *reqTrig* sub-property of *operationalisation*.



**Condition:** *reqPost* (sub-property of *operationalisation*) and *domPost* (sub-property of *operation*) holds.

**Action:** object explicit and implicit attributes are taken as the input for the operation.

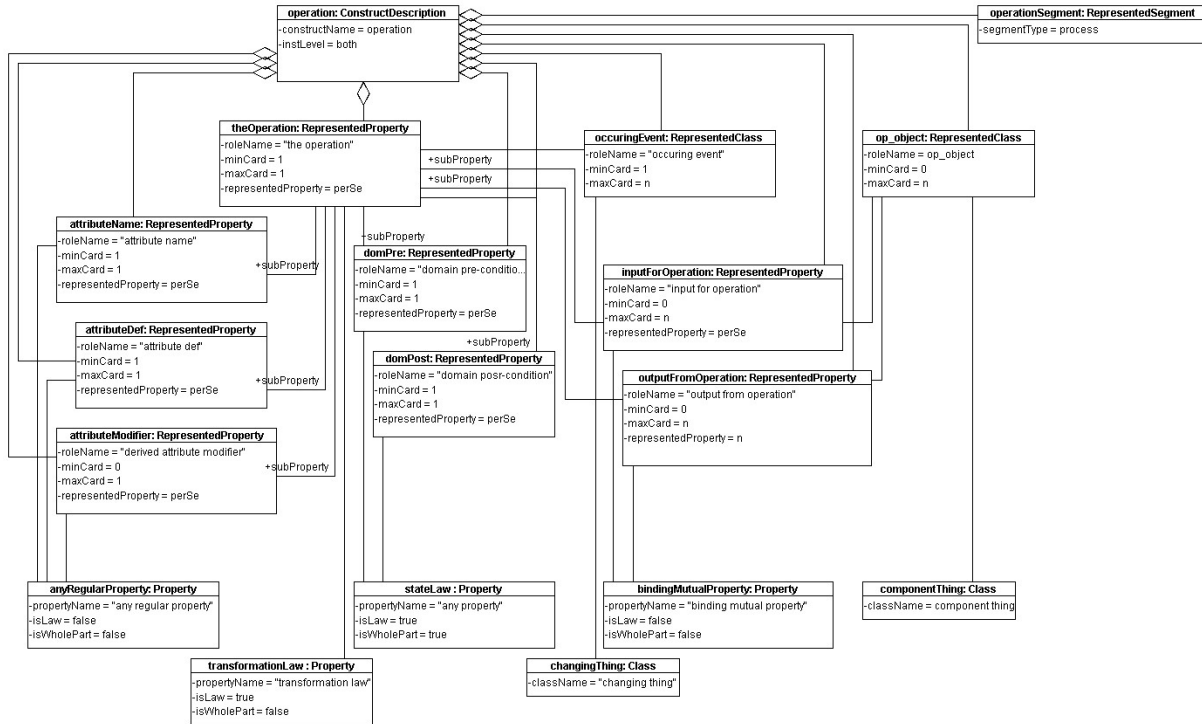
## Modality (permission, recommendation etc)

Regular assertion

## 4. Open Issues

TBF – *Dependency* constraint between agents as through goal or through operation.

TBF – A *goal* defines a set of admissible histories in the composed system. Intuitively, a history is a temporal sequence of states of the system. Specify *Scenario*, *Snapshot*, *Interaction*, *Source*, *Target*, and *State transition* constraints. This is related to *Agent*, *Event*, and *Operation* constraints.



## KAOS : Operationalisation

<b>Document type:</b>	Working document
<b>Domain/Task/Topic:</b>	DEM / UEMML / Approaches
<b>Version:</b>	
<b>Date:</b>	2005.11.30
<b>Status:</b>	2 <sup>nd</sup> iteration
<b>Authors:</b>	Raimundas Matulevičius
<b>Distribution list:</b>	DEM
<b>Document history:</b>	

The *Operationalisation* meta-relationship is an AND/OR relationship between goals and required pre, trigger, and post conditions of operations. Intuitively, a set of required pre, trigger, and post conditions operationalises a goal if satisfying the required conditions on operations guarantees that the goal is satisfied.

### 1. Preamble

**Builds on**

**Built on by**

**Construct name**

Operationalisation

**Alternative construct names**

**Related, but distinct construct names**

**Related terms**

**Language**

KAOS,  
<http://www2.info.ucl.ac.be/research/projects/AVL/ReqEng.html>

**Diagram type**

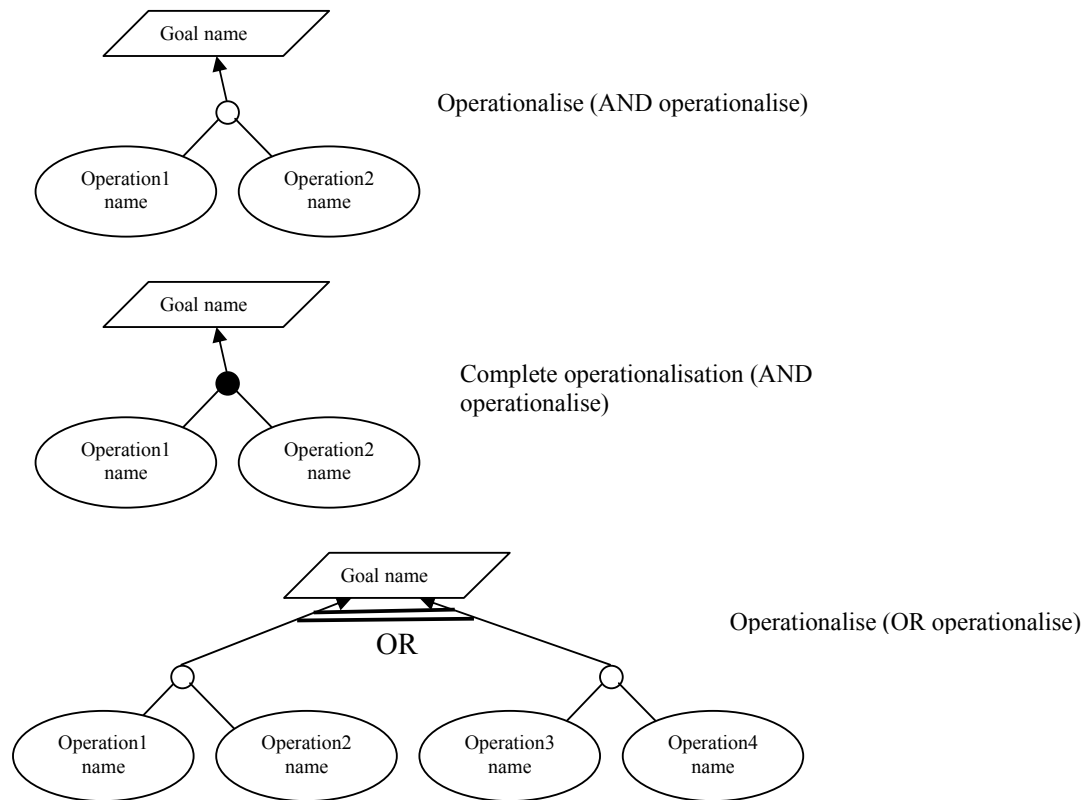
Operation model

### 2. Presentation

**Builds on**

**Built on by**

## Icon, line style, text



## User-definable attributes

[1:1] **Complete:** Boolean. Indicate whether the operationalisation is *arguably sufficient* (value "complete") or not arguably sufficient (value "undetermined").

[0:1] **AltName:** String ="". To name the corresponding alternative for further reference. In case a goal is operationalised into multiple alternative operationalisations this meta-attribute is mandatory.

## Relations to other constructs

Belongs to 1..1 operation model.

1:1 [1:1], op\_goal. *Goal* is operationalised through the *operation*.

0:n [1:1], op\_operation. *Operation* operationalises the *goal*.

## Diagram layout conventions

## Other usage conventions

## 3. Representation

### Builds on

Goal

Operation

## Built on by

## Instantiation level

Instance and type level

## Classes of things

- 1:1, “*goalOwner*” **played by** *StakeholderThing*.  
Describing *goal owner* which holds the goal. Class *StakeholderThing* has a characteristic *holds goal*.  
*StakeholderThing* is subclass of the *BWW-HumanThing* (specified in *goal* template).
- 1:1, “*occurringEvent*” **played by** *ChangingThing*.  
Operationalisation’s *reqTrig* includes a predicate *Occurs* on instances of that event.
- 1:1, “*op\_object*” **played by** *ComponentThing*.  
Operation gets inputs as object attributes and produces outputs as object attributes.

## Properties (and relationships)

- 1:1, “*theGoal*” **played by** *ComplexLawProperty*.  
**Belongs to:** 0:1 [1:1], *goalOwner*.  
**Law:** restricts the the possible values of the *object* attributes.  
Representing the goal which is held by a goal owner.
- 1:1, “*terminalGoal*” **played by** *ComplexLawProperty*.  
**Sub-property:** 1:1 [1:1], *theAssignedGoal*.  
**State law:**  $\forall g \in \text{Goal}, \forall a \in \text{Assignment}, a.\text{assignedGoal} = g \Rightarrow \neg \exists gr \in \text{G-refinement}: gr.\text{superGoal} = g$   
Only terminal goals can be assigned.
- 1:1, “*operationalisedOperation*” **played by** *TransformationLaw*.  
**Sub-property:** *inputForOperation*.  
**Sub-property:** *outputForOperation*.  
**Belongs to:** 0:n[0:n] *occurringEvent*.  
**Transformation law:** operation changes the states of the object.  
Describing the operationalised operation.  
**Also represented by** *operation*.
- 0:n [0:n] “*inputForOperation*” **played by** *BindingMutualProperty*.  
**Belongs to:** *op\_object*.  
Describing input for operation.  
**Also represented by:** *Inputs*.
- 0:n [0:n] “*outputForOperation*” **played by** *BindingMutualProperty*.  
**Belongs to:** *op\_object*.  
Describing output for operation.  
**Also represented by:** *Outputs*.
- 1:1, “*theOperationalisation*” **played by** *ComplexMutualProperty*.  
**Type:** *AND/OR relationship*.  
**Sub-property:** 1:1[0:n] *terminalGoal*.  
Describing *operationalisation*. Operationalisation is a complex mutual property between goal owner, object and event.
- 1:1 [1:1], “*attributeComplete*” **played by** *AnyRegularProperty*.  
**Sub-property:** *theOperationalisation*.  
Represents *operationalisation* attribute *complete*.

0:1 [1:1], “*attributeAltName*” **played by** *AnyRegularProperty*.

**Sub-property:** *theOperationalisation*.

Represents *operationalisation* attribute *altName*.

1:n [1:1], “*op\_operation*” **played by** *ComplexProperty*.

**Sub-property:** 1:1 [1:n] *theOperationalisation*.

**Sub-property:** 1:1 [1:n] *operationalisedOperation*.

1:1 [1:1] “*reqPre*” **played by** *StateLaw*.

**Sub-property:** 1:1 [1:1] *op\_operation*.

Necessary condition that needs to be true when the operation is applied for the corresponding operationalised goal to be satisfied.

1:1 [1:1] “*reqPost*” **played by** *StateLaw*.

**Sub-property:** 1:1 [1:1] *op\_operation*.

Condition that needs to be established by the operation in its final state for the corresponding operationalised goal to be satisfied.

1:1 [1:1] “*reqTrig*” **played by** *TransformationLaw*.

**Sub-property:** 1:1 [1:1] *op\_operation*.

**Sub-property:** 0:n [0:n] *occurringEvent*.

Sufficient condition that requires the operation to be immediately applied for the corresponding operationalised goal to be satisfied.

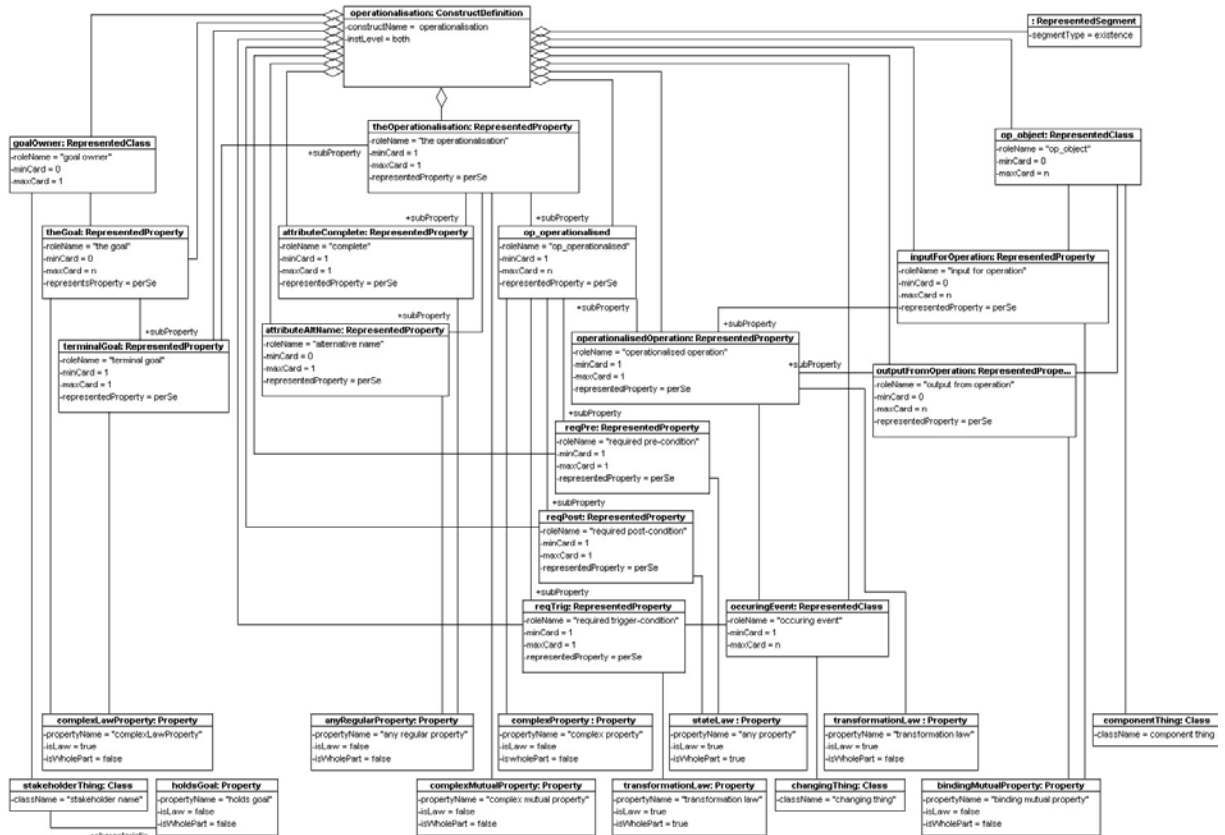
## Behaviour

Existence

## Modality (permission, recommendation etc)

Regular assertion

## 4. Open Issues





## KAOS : Output

<b>Document type:</b>	Working document
<b>Domain/Task/Topic:</b>	DEM / UEMML / Approaches
<b>Version:</b>	
<b>Date:</b>	2005.11.30
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<b>Authors:</b>	Raimundas Matulevičius
<b>Distribution list:</b>	DEM
<b>Document history:</b>	

An object is among the *outputs* of an operation if it is among the sorts making up the co-domain of the relation defined by the operation.

### 1. Preamble

**Builds on**

**Built on by**

**Construct name**

Outputs

**Alternative construct names**

**Related, but distinct construct names**

**Related terms**

*Inputs* : An *object* is among the *inputs* of an *operation* if it is among the sorts making up the domain of the relation defined by the *operation*.

**Language**

KAOS,  
<http://www2.info.ucl.ac.be/research/projects/AVL/ReqEng.html>

**Diagram type**

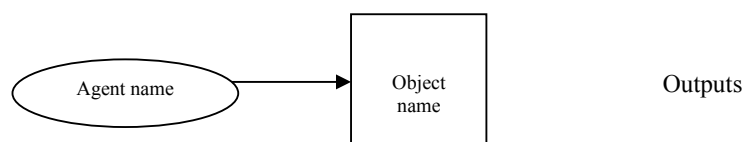
Operation model

### 2. Presentation

**Builds on**

**Built on by**

**Icon, line style, text**





## User-definable attributes

[0:1] *WhichAtt* : String = “”. Indicate which attributes of the object are specifically monitored.

## Relations to other constructs

- Belongs to 1..1 operation model.
- 0:n [1:1], Object. *Object* has output from an *operation*.
- 0:n [1:1], Operation. *Operation* outputs *object* attributes (changes its value).

## Diagram layout conventions

## Other usage conventions

# 3. Representation

## Builds on

## Built on by

## Instantiation level

Type level

## Classes of things

1:1 “*outObject*” **played by** *ComponentThing*.  
Represents *object*, which is output from operation.

0:n, “*causingEvent*” **played by** *ChangingThing*.

## Properties (and relationships)

1:1, “*theOutput*” **played by** *BindingMutualProperty*.

**Belongs to:** 0:n [1:1] *object*.

Describing *output*. Output is a binding mutual property between the object which receives output from operation and the event which causes this operation.

1:n, “*explicitObjAttribute*” **played by** *AnyProperty*.

**Belongs to:** *outObject*.

**Sub-property of:** *theOutput*.

Defines explicitly which attribute of the object is an output.

1:n, “*implicitObjAttribute*” **played by** *AnyProperty*.

**Belongs to:** *outObject*.

**Sub-property of:** *theOutput*.

Does not define explicitly which attribute of the object is an output.

0:1, “*attributeWhichAtt*” **played by** *AnyRegularProperty*.

**Sub-property:** *theOutput*.

Representing the *output* attribute *whichAtt*.

0:n [1:1], “*fromOperation*” **played by** *TransformationLaw*.

**Belongs to:** *causingEvent*.

**Sub-property:** *theOutput*.

**Transformation law:** operation produces output.

Describing the operation which has output.

**Also represented by:** *operation*.

## Behaviour

Existence

**Modality (permission, recommendation etc)**

Regular assertion

**4. Open Issues**



## KAOS : Performance

<b>Document type:</b>	Working document
<b>Domain/Task/Topic:</b>	DEM / UEMML / Approaches
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<b>Date:</b>	2005.11.30
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<b>Authors:</b>	Raimundas Matulevičius
<b>Distribution list:</b>	DEM
<b>Document history:</b>	

An operation is related to the agent that can initiate it through a *performance* link. Performance is an OR meta-relationship linking *agents* to *operations*.

### 1. Preamble

**Builds on**

**Built on by**

**Construct name**

Performance

**Alternative construct names**

Performs

**Related, but distinct construct names**

**Related terms**

**Language**

KAOS,  
<http://www2.info.ucl.ac.be/research/projects/AVL/ReqEng.html>

**Diagram type**

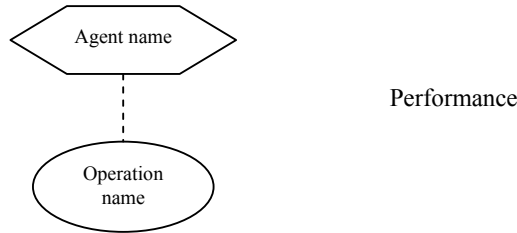
Agent model

### 2. Presentation

**Builds on**

**Built on by**

**Icon, line style, text**



## User-definable attributes

[0:1] *Agent* : Agent. Declare the agent.

[0:1] *AltName* : String = "". Name of alternative OR-assignments.

## Relations to other constructs

- Belongs to 1..1 agent model.
- 1:1 [1:1], Agent. *Agent* performs *operation*.
- 1:n [1:1], Operation. *Operation* is performed by agent.

## Diagram layout conventions

## Other usage conventions

# 3. Representation

## Builds on

Agent

## Built on by

## Instantiation level

Type level

## Classes of things

1:1, “*goalOwner*” **played by** *StakeholderThing*.

Describing *goal owner* which holds the goal. Class *StakeholderThing* has a characteristic *holds goal*.  
*StakeholderThing* is subclass of the *BWW-HumanThing*.

1:1 “*responsibleAgent*” **played by** *ActiveComponentThing*.

Represents the responsible agent.

## Properties (and relationships)

1:1, “*theGoal*” **played by** *ComplexLawProperty*.

**Belongs to:** 0:1 [1:1], *goalOwner*.

**Law:** restricts the the possible values of the *object* attributes.  
Representing the goal which is held by a goal owner.

1:1, “*terminalGoal*” **played by** *StateLaw*.

**Belongs to:** 0:1 [1:1], *goalOwner*.

**Sub-property:** 1:1 [1:1], *theGoal*.

**State law:**  $\forall g \in \text{Goal}, \forall a \in \text{Assignment}, a.\text{assignedGoal} = g$   
 $\Rightarrow \neg \exists gr \in \text{G-refinement}: gr.\text{superGoal} = g$

Only terminal goals can be assigned.

1:1, “*thePerformance*” **played by** *ComplexMutualProperty*.

**Type:** OR-relationship.

**Belongs to:** 1:n [1:1] *responsibleAgent*.

Representing the performance. Performance is a complex mutual property of the responsible agent and the goal owner. Agent performs the operation in order to satisfy the goal.

0:1, “*attributeAgent*” **played by** *AnyRegularProperty*.

**Sub-property:** *thePerformance*.

Representing the *performance* attribute *agent*.

0:1, “*attributeAltName*” **played by** *AnyRegularProperty*.

**Sub-property:** *thePerformance*.

Represents *performance* attribute *altName*.

1:1 [1:1], “*performedOperation*” **played by** *TransformationLaw*.

**Sub-property:** *thePerformance*.

**Transformation law:** agent performs operation to satisfy the goal.

Describing the operation which is performed by agent.

**Also represented by:** *operation*.

1:n [1:1], “*operationalisation*” **played by** *ComplexMutualProperty*.

**Sub-property:** *performedOperation*.

**Sub-property:** *terminalGoal*.

Describing the operationalisation relationship.

**Also represented by:** *operationalisation*.

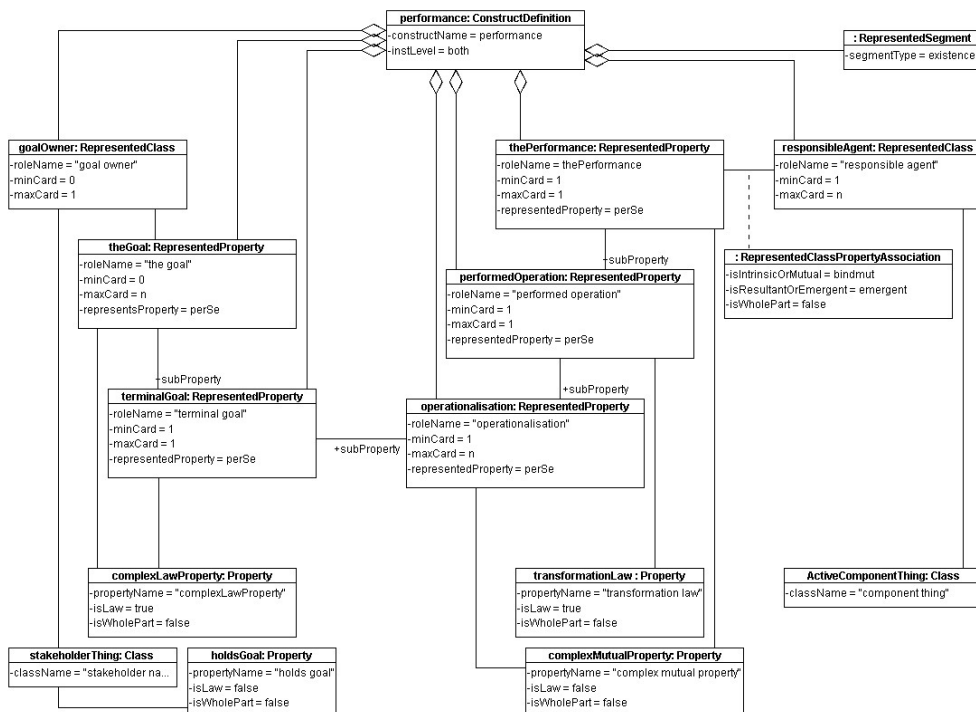
## Behaviour

Existence

## Modality (permission, recommendation etc)

Regular assertion

## 4. Open Issues





## KAOS : Requirement

<b>Document type:</b>	Working document
<b>Domain/Task/Topic:</b>	DEM / UEMML / Approaches
<b>Version:</b>	
<b>Date:</b>	2005.11.30
<b>Status:</b>	2 <sup>nd</sup> iteration
<b>Authors:</b>	Raimundas Matulevičius
<b>Distribution list:</b>	DEM
<b>Document history:</b>	

A *requirement* is a goal assigned to an agent in the software-to-be.

### 1. Preamble

#### **Builds on**

Goal

#### **Built on by**

#### **Construct name**

Requirement

#### **Alternative construct names**

#### **Related, but distinct construct names**

*Terminal goal*: goal which has no G-requirement.

#### **Related terms**

*Expectation (assumption)*: a goal assigned to an agent in the environment.

*Softgoal*: a goal that cannot be said to be satisfied in a clearcut sense.

**Comment**: can a requirement be a softgoal?

*Maintain goal*: a goal requiring that some property always holds.

*Avoid goal*: a goal requiring that some property never holds.

*Achieve goal*: a goal requiring that some property eventually hold.

*Cease goal*: a goal requiring that some property eventually stops to hold.

#### **Language**

KAOS,

<http://www2.info.ucl.ac.be/research/projects/AVL/ReqEng.html>

#### **Diagram type**

Goal model



## 2. Presentation

**Builds on**

**Built on by**

**Icon, line style, text**



Requirement

### User-definable attributes

Requirement inherits all the attributes of the goal.

### Relations to other constructs

- Belongs 1:1 to goal model.
- 1:n [1:n], *responsible* : *software agent*. *Requirement* is assigned through responsibility relationship to a *software agent*.

### Diagram layout conventions

### Other usage conventions

## 3. Representation

**Builds on**

**Comment:** *Requirement* is a goal and has most of the goal classes and properties. But *requirement* is also a terminal goal, so it has no G-refinement.

**Built on by**

**Instantiation level**

Instance level

### Classes of things

1:1, “*softwareAgent*” **played by** *ActiveComponentThing*.  
Describing the agent a *requirement* is assigned.

### Properties (and relationships)

1:1, “*theRequirement*” **played by** *ComplexStateLaw*.

**Belongs to:** 0:1 [0:n] *softwareAgent*.

**Belongs to:** 0:1 [1:1] *goalOwner*.

**State law:** Is restricted by the assignement relationship. A requirement himself restricts state of the concerned object.

Representing the *requirement*. Requirement as a goal, has a goal owner.

1:1, “*isTerminalGoal*” **played by** *StateLaw*.

**Sub-property:** 1:1 [1:1], *theRequirement*.

**State law:**  $\forall g \in \text{Goal}, \forall a \in \text{Assignment}, a.\text{assignedGoal} = g$

$\Rightarrow \neg \exists \text{ gr} \in \text{G-refinement: gr.superGoal} = \text{g}$

*Requirement* is a terminal *goal* which means that an *requirement* can not have G-refinement.

## Behaviour

Existence

## Modality (permission, recommendation etc)

**Intention** of a goal owner;

**Obligation** of a *software agent*.

## 4. Open Issues



## KAOS : Softgoal

<b>Document type:</b>	Working document
<b>Domain/Task/Topic:</b>	DEM / UEMML / Approaches
<b>Version:</b>	
<b>Date:</b>	2005.11.30
<b>Status:</b>	2 <sup>nd</sup> iteration
<b>Authors:</b>	Raimundas Matulevičius
<b>Distribution list:</b>	DEM
<b>Document history:</b>	

A *softgoal* is a goal that cannot be said to be satisfied in a clearcut sense. It prescribes classes of preferred behaviour.

### 1. Preamble

#### Builds on

Goal

#### Built on by

#### Construct name

Softgoal

#### Alternative construct names

Goal

Preferred behaviour

#### Related, but distinct construct names

#### Related terms

*Requirement* : a goal assigned to an agent in the software to be.

*Assumption* : a goal assigned to an agent in the environment.

#### Language

KAOS,

<http://www2.info.ucl.ac.be/research/projects/AVL/ReqEng.html>

#### Diagram type

Goal model

### 2. Presentation

#### Builds on

#### Built on by

## Icon, line style, text



Softgoal

## User-definable attributes

[0:1] *Type* : set\_of [*Minimize, Maximize, Reduce, Increase, Improve*]. Describes type of the softgoal.

## Relations to other constructs

## Diagram layout conventions

## Other usage conventions

# 3. Semantics

## Builds on

**Comment:** Softgoals can be And/Or refined like any other KAOS goals, conflicts between softgoals goals can also be captured. An important research issue concerns the precise definition of optimization goals, reasoning techniques about softgoals, and the role of such goals in selecting among alternative goal refinements.

## Built on by

## Instantiation level

Instance level

## Classes of things

## Properties (and relationships)

1:1, “*theSoftGoal*” **played by** *ComplexLawProperty*.  
Representing the *softgoal*.

1:1, “*notSatisfiedClearly*” **played by** *AnyProperty*.  
The *softgoal* has property (rather feature) not to be satisfied in a clearcut sense.

0:1 [1:1], “*attributeType*” **played by** *AnyRegularProperty*.  
**Sub-property:** *theSoftGoal*.  
Represents *goal* attribute *type*.

## Behaviour

Existence

## Modality (permission, recommendation etc)

**Intention of** a goal owner;

# 4. Open Issues

**Comment:** Further investigation about all softgoal (as goal) features is needed!

## KAOS : Software agent

<b>Document type:</b>	Working document
<b>Domain/Task/Topic:</b>	DEM / UEMML / Approaches
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<b>Authors:</b>	Raimundas Matulevičius
<b>Distribution list:</b>	DEM
<b>Document history:</b>	

*Software agent* is an agent in the system-to-be.

### 1. Preamble

#### Builds on

Agent

#### Built on by

#### Construct name

Software agent

#### Alternative construct names

Agent in the system-to-be

#### Related, but distinct construct names

#### Related terms

- *Agents* : active objects capable of performing operations.
- *Environment agent* : e.g., pre-existing software component, sensor, actuator, human, organisational unit, etc.

#### Language

KAOS,  
<http://www2.info.ucl.ac.be/research/projects/AVL/ReqEng.html>

#### Diagram type

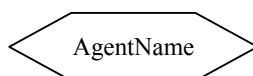
Agent model

### 2. Presentation

#### Builds on

#### Built on by

#### Icon, line style, text



Software agent

**User-definable attributes**

**Relations to other constructs**

**Diagram layout conventions**

**Other usage conventions**

### **3. Representation**

**Builds on**

**Built on by**

**Instantiation level**

Type level

**Classes of things**

1:1, “*theSoftwareAgent*” **played by** *ComponentSoftwareThing*.

Representing the *software agent*. *Software agents* are *agents* and inherits all agent attributes and properties.

**Properties (and relationships)**

**Behaviour**

Existence

**Modality (permission, recommendation etc)**

Regular assertion

### **4. Open Issues**







